

Chapter 5

Link Layer

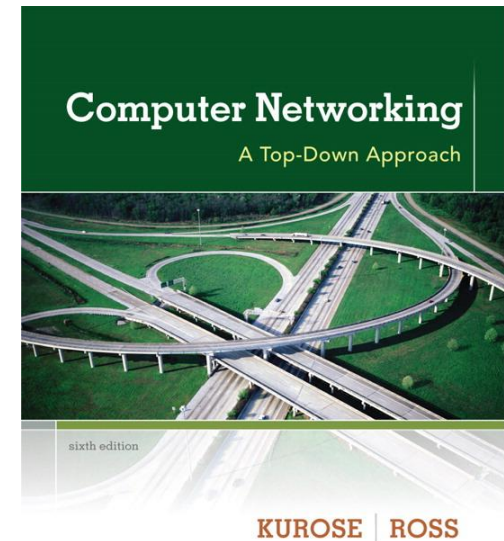
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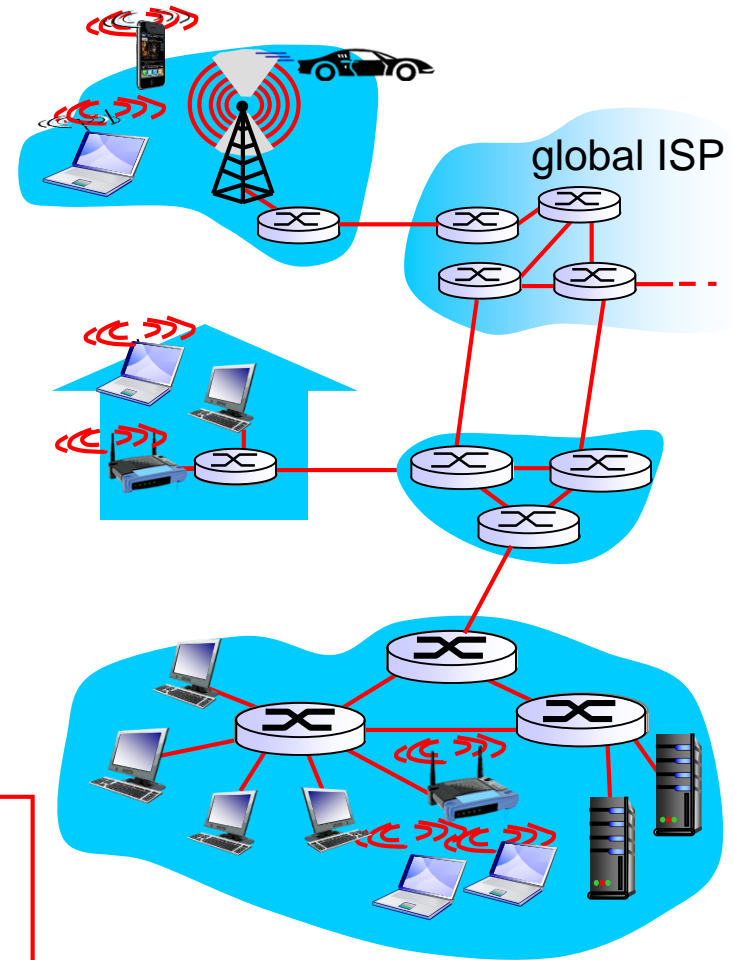
**Computer
Networking: A Top
Down Approach**
6th edition
Jim Kurose, Keith Ross
Addison-Wesley
March 2012

Link layer: introduction

terminology:

- ❖ hosts and routers: **nodes**
- ❖ communication channels that connect adjacent nodes along communication path: **links**
 - wired links
 - wireless links
 - LANs
- ❖ layer-2 packet: **frame**, encapsulates datagram

data-link layer has responsibility of transferring datagram from one node to *physically adjacent* node over a link



Link layer services

❖ *framing, link access:*

- encapsulate datagram into frame, adding header, trailer
- channel access if shared medium
- “MAC” addresses used in frame headers to identify source, dest
 - different from IP address!

❖ *reliable delivery between adjacent nodes*

- we learned how to do this already (chapter 3)!
- seldom used on low bit-error link (fiber, some twisted pair)
- wireless links: high error rates
 - **Q:** why both link-level and end-end reliability?

Link layer services (more)

❖ *flow control:*

- pacing between adjacent sending and receiving nodes

❖ *error detection:*

- errors caused by signal attenuation, noise.
- receiver detects presence of errors:
 - signals sender for retransmission or drops frame

❖ *error correction:*

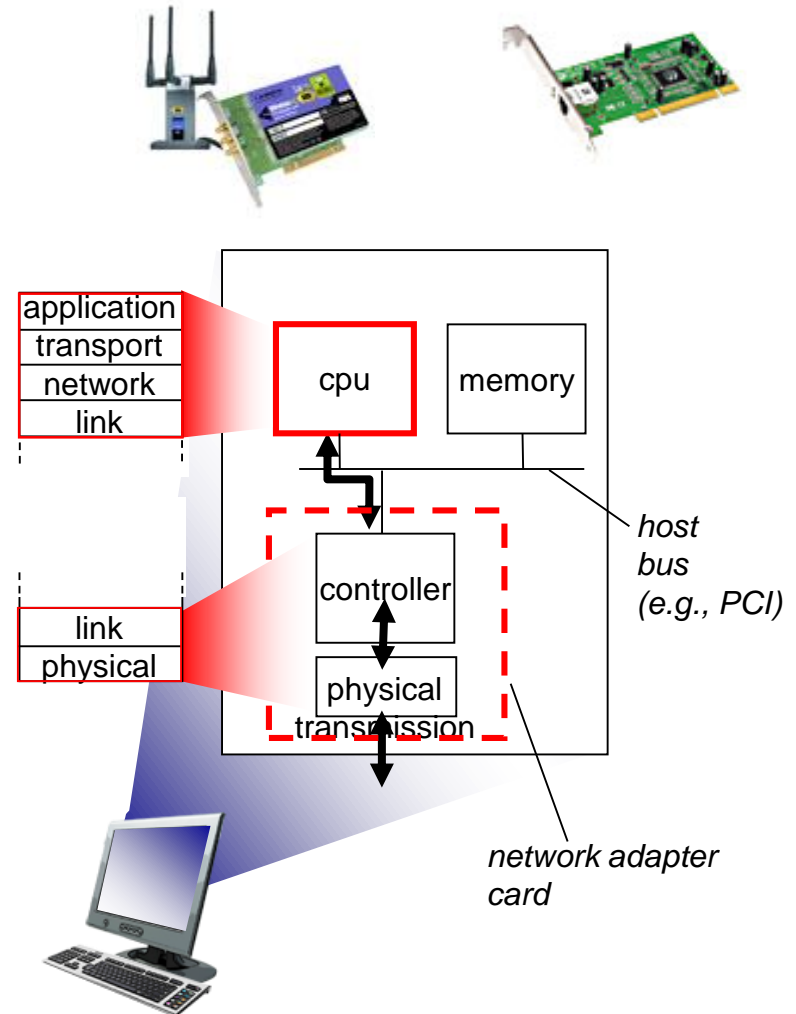
- receiver identifies *and corrects* bit error(s) without resorting to retransmission

❖ *half-duplex and full-duplex*

- with half duplex, nodes at both ends of link can transmit, but not at same time

Where is the link layer implemented?

- ❖ in each and every host
- ❖ link layer implemented in “adaptor” (aka *network interface card* NIC) or on a chip
 - Ethernet card, 802.11 card; Ethernet chipset
 - implements link, physical layer
- ❖ attaches into host's system buses
- ❖ combination of hardware, software, firmware



Link layer, LANs: outline

5.1 introduction, services

5.2 error detection,
correction

5.3 multiple access
protocols

5.4 LANs

- addressing, ARP
- Ethernet
- switches
- VLANs

5.5 link virtualization:
MPLS

5.6 data center
networking

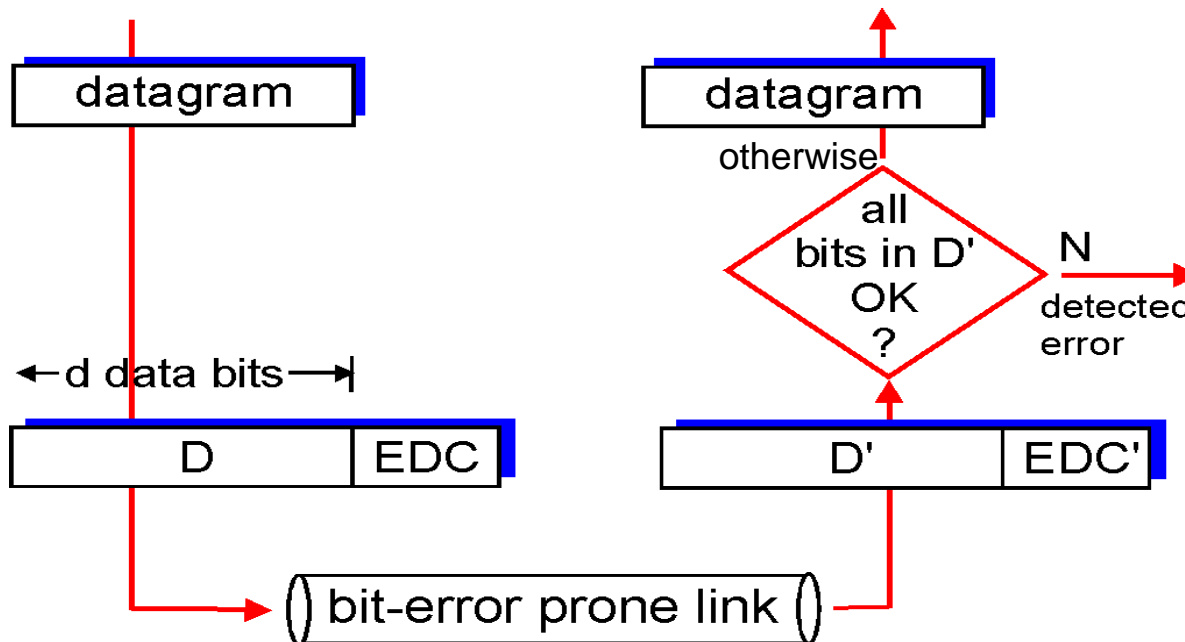
5.7 a day in the life of a
web request

Error detection

EDC= Error Detection and Correction bits (redundancy)

D = Data protected by error checking, may include header fields

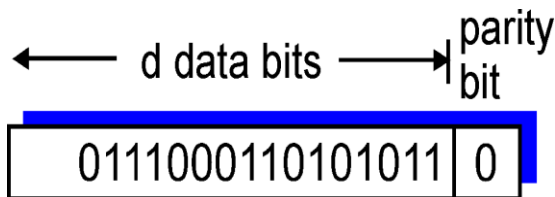
- Error detection not 100% reliable!
 - protocol may miss some errors, but rarely
 - larger EDC field yields better detection and correction



Parity checking

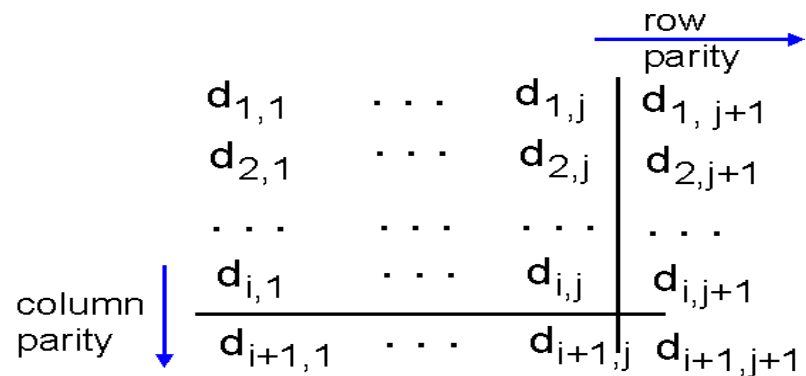
single bit parity:

- ❖ detect single bit errors



two-dimensional bit parity:

- ❖ detect and correct single bit errors



| | | | | | |
|---|---|---|---|---|---|
| 1 | 0 | 1 | 0 | 1 | 1 |
| 1 | 1 | 1 | 1 | 0 | 0 |
| 0 | 1 | 1 | 1 | 0 | 1 |
| 0 | 0 | 1 | 0 | 1 | 0 |

no errors

| | | | | | |
|---|---|---|---|---|---|
| 1 | 0 | 1 | 0 | 1 | 1 |
| 1 | 0 | 1 | 1 | 0 | 0 |
| 0 | 1 | 1 | 1 | 0 | 1 |
| 0 | 0 | 1 | 0 | 1 | 0 |

parity
error

*correctable
single bit error*

Internet checksum (review)

goal: detect “errors” (e.g., flipped bits) in transmitted packet
(note: used at transport layer *only*)

sender:

- ❖ treat segment contents as sequence of 16-bit integers
- ❖ checksum: addition (1’s complement sum) of segment contents
- ❖ sender puts checksum value into UDP checksum field

receiver:

- ❖ compute checksum of received segment
- ❖ check if computed checksum equals checksum field value:
 - NO - error detected
 - YES - no error detected.
But maybe errors nonetheless?

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Multiple access links, protocols

two types of “links”:

- ❖ point-to-point

- PPP for dial-up access
- point-to-point link between Ethernet switch, host

- ❖ *broadcast (shared wire or medium)*

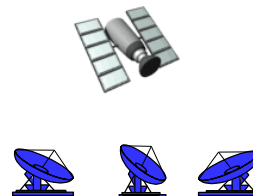
- old-fashioned Ethernet
- upstream HFC
- 802.11 wireless LAN



shared wire (e.g.,
cabled Ethernet)



shared RF
(e.g., 802.11 WiFi)



shared RF
(satellite)



humans at a
cocktail party
(shared air, acoustical)

Multiple access protocols

- ❖ single shared broadcast channel
- ❖ two or more simultaneous transmissions by nodes: interference
 - *collision* if node receives two or more signals at the same time

multiple access protocol

- ❖ distributed algorithm that determines how nodes share channel, i.e., determine when node can transmit
- ❖ communication about channel sharing must use channel itself!
 - no out-of-band channel for coordination

An ideal multiple access protocol

given: broadcast channel of rate R bps

desiderata:

1. when one node wants to transmit, it can send at rate R .
2. when M nodes want to transmit, each can send at average rate R/M
3. fully decentralized:
 - no special node to coordinate transmissions
 - no synchronization of clocks, slots
4. simple

MAC protocols: taxonomy

three broad classes:

❖ *channel partitioning*

- divide channel into smaller “pieces” (time slots, frequency, code)
- allocate piece to node for exclusive use

❖ *random access*

- channel not divided, allow collisions
- “recover” from collisions

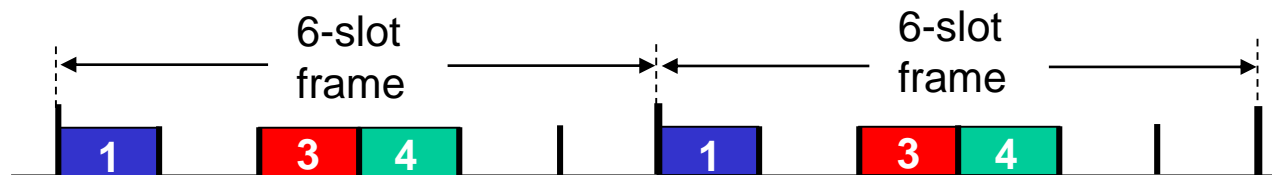
❖ *“taking turns”*

- nodes take turns, but nodes with more to send can take longer turns

Channel partitioning MAC protocols: TDMA

TDMA: time division multiple access

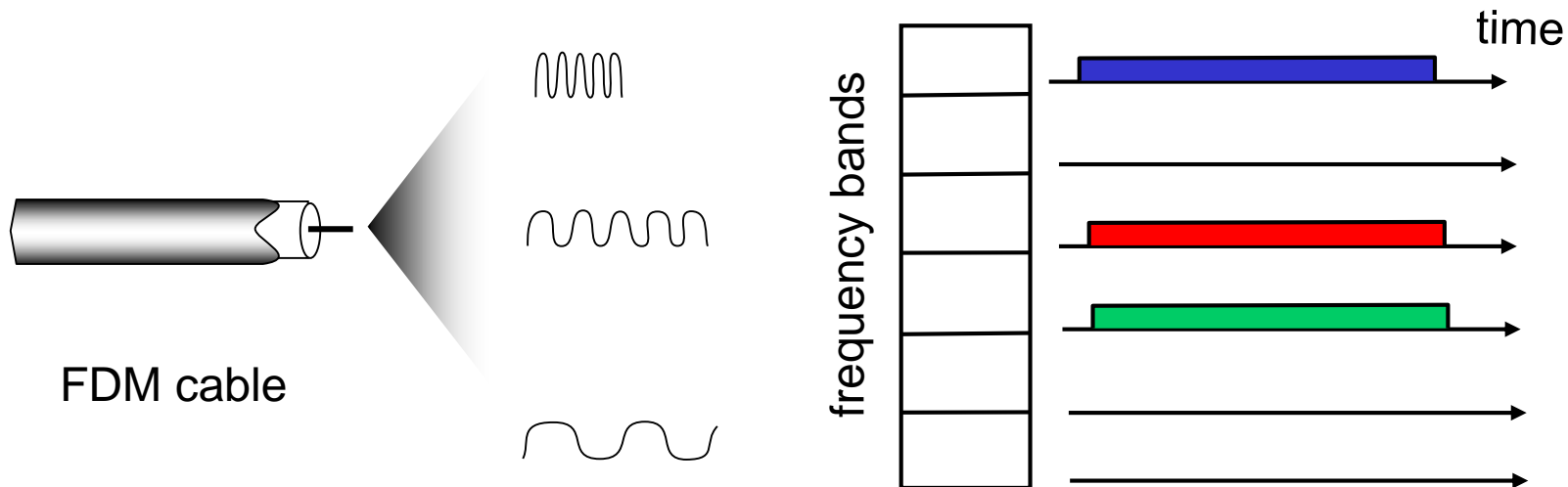
- ❖ access to channel in "rounds"
- ❖ each station gets fixed length slot (length = pkt trans time) in each round
- ❖ unused slots go idle
- ❖ example: 6-station LAN, 1,3,4 have pkt, slots 2,5,6 idle



Channel partitioning MAC protocols: FDMA

FDMA: frequency division multiple access

- ❖ channel spectrum divided into frequency bands
- ❖ each station assigned fixed frequency band
- ❖ unused transmission time in frequency bands go idle
- ❖ example: 6-station LAN, 1,3,4 have pkt, frequency bands 2,5,6 idle



Random access protocols

- ❖ when node has packet to send
 - transmit at full channel data rate R .
 - no *a priori* coordination among nodes
- ❖ two or more transmitting nodes → “collision”,
- ❖ **random access MAC protocol** specifies:
 - how to detect collisions
 - how to recover from collisions (e.g., via delayed retransmissions)
- ❖ examples of random access MAC protocols:
 - slotted ALOHA
 - ALOHA
 - CSMA, CSMA/CD, CSMA/CA

Slotted ALOHA

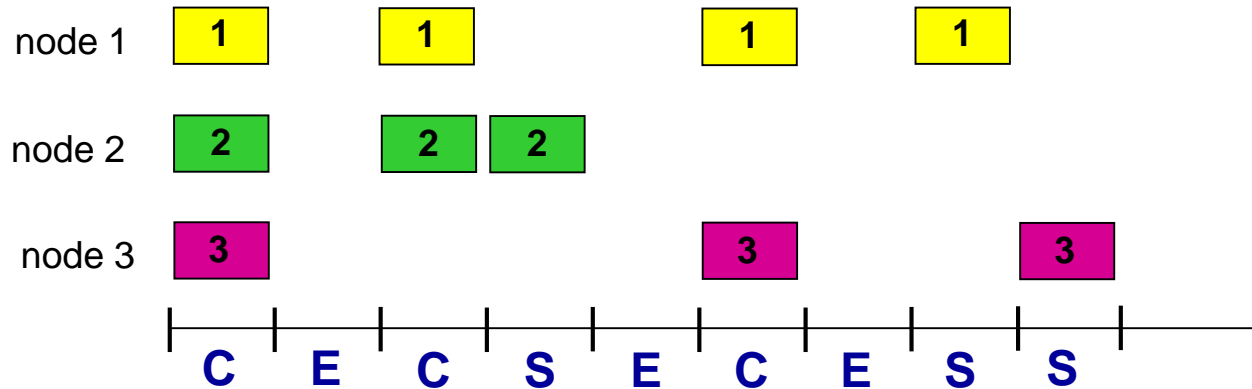
assumptions:

- ❖ all frames same size
- ❖ time divided into equal size slots (time to transmit 1 frame)
- ❖ nodes start to transmit only slot beginning
- ❖ nodes are synchronized
- ❖ if 2 or more nodes transmit in slot, all nodes detect collision

operation:

- ❖ when node obtains fresh frame, transmits in next slot
 - *if no collision:* node can send new frame in next slot
 - *if collision:* node retransmits frame in each subsequent slot with prob. p until success

Slotted ALOHA



Pros:

- ❖ single active node can continuously transmit at full rate of channel
- ❖ highly decentralized: only slots in nodes need to be in sync
- ❖ simple

Cons:

- ❖ collisions, wasting slots
- ❖ idle slots
- ❖ nodes may be able to detect collision in less than time to transmit packet
- ❖ clock synchronization

Slotted ALOHA: efficiency

efficiency: long-run fraction of successful slots (many nodes, all with many frames to send)

- ❖ suppose: N nodes with many frames to send, each transmits in slot with probability p
- ❖ prob that given node has success in a slot = $p(1-p)^{N-1}$
- ❖ prob that *any* node has a success = $Np(1-p)^{N-1}$

- ❖ max efficiency: find p^* that maximizes $Np(1-p)^{N-1}$
- ❖ for many nodes, take limit of $Np^*(1-p^*)^{N-1}$ as N goes to infinity, gives:

$$\text{max efficiency} = 1/e = .37$$

at best: channel used for useful transmissions 37% of time!



CSMA (carrier sense multiple access)

CSMA: listen before transmit:

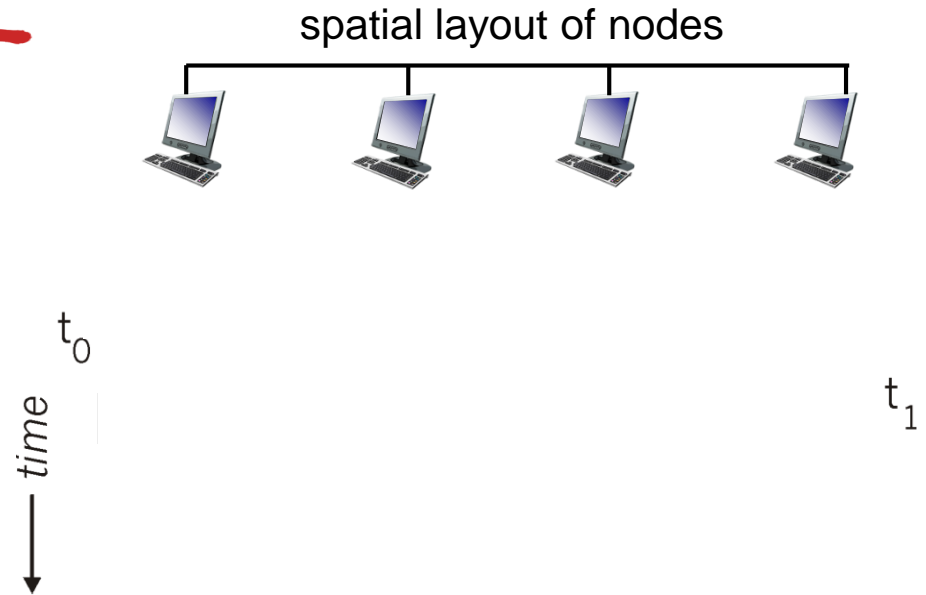
if channel sensed idle: transmit entire frame

❖ if channel sensed busy, defer transmission

❖ human analogy: don't interrupt others!

CSMA collisions

- ❖ collisions *can* still occur: propagation delay means two nodes may not hear each other's transmission
- ❖ collision: entire packet transmission time wasted
 - distance & propagation delay play role in determining collision probability

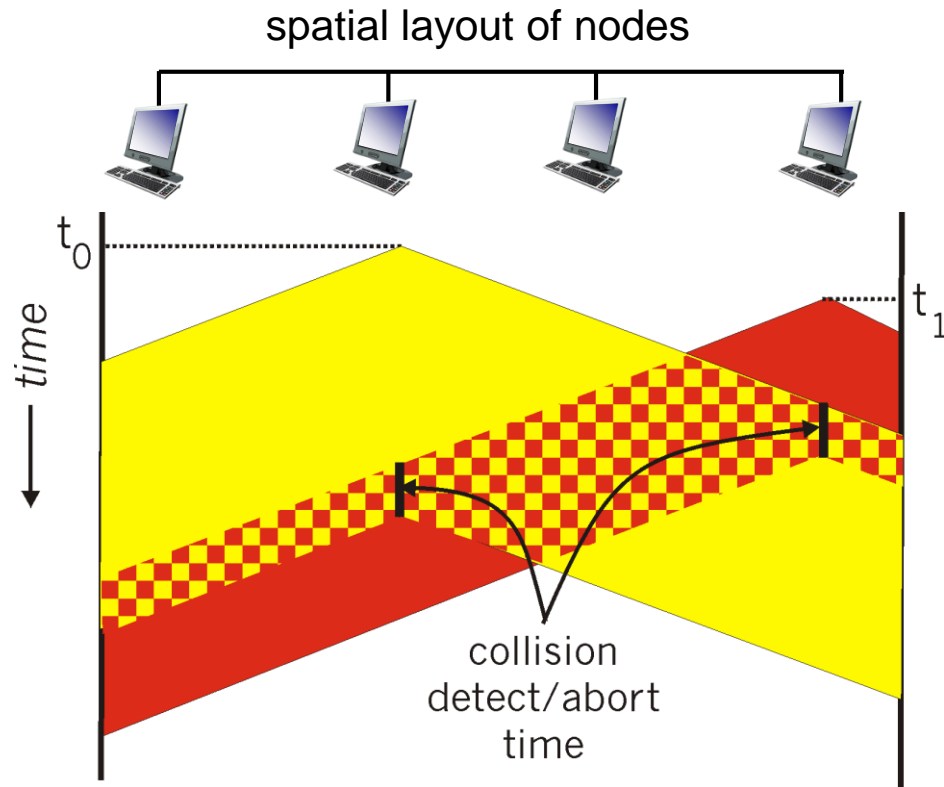


CSMA/CD (collision detection)

CSMA/CD: carrier sensing, deferral as in CSMA

- collisions *detected* within short time
- colliding transmissions aborted, reducing channel wastage
- ❖ collision detection:
 - easy in wired LANs: measure signal strengths, compare transmitted, received signals
 - difficult in wireless LANs: received signal strength overwhelmed by local transmission strength
- ❖ human analogy: the polite conversationalist

CSMA/CD (collision detection)



Ethernet CSMA/CD algorithm

1. NIC receives datagram from network layer, creates frame
2. If NIC senses channel idle, starts frame transmission. If NIC senses channel busy, waits until channel idle, then transmits.
3. If NIC transmits entire frame without detecting another transmission, NIC is done with frame !
4. If NIC detects another transmission while transmitting, aborts and sends jam signal
5. After aborting, NIC enters *binary (exponential) backoff*:
 - after m th collision, NIC chooses K at random from $\{0, 1, 2, \dots, 2^m - 1\}$. NIC waits $K \cdot 512$ bit times, returns to Step 2
 - longer backoff interval with more collisions

CSMA/CD efficiency

- ❖ T_{prop} = max prop delay between 2 nodes in LAN
- ❖ t_{trans} = time to transmit max-size frame

$$\text{efficiency} = \frac{1}{1 + 5t_{\text{prop}}/t_{\text{trans}}}$$

- ❖ efficiency goes to 1
 - as t_{prop} goes to 0
 - as t_{trans} goes to infinity
- ❖ better performance than ALOHA: and simple, cheap, decentralized!

“Taking turns” MAC protocols

channel partitioning MAC protocols:

- share channel *efficiently* and *fairly* at high load
- inefficient at low load: delay in channel access, 1/N bandwidth allocated even if only 1 active node!

random access MAC protocols

- efficient at low load: single node can fully utilize channel
- high load: collision overhead

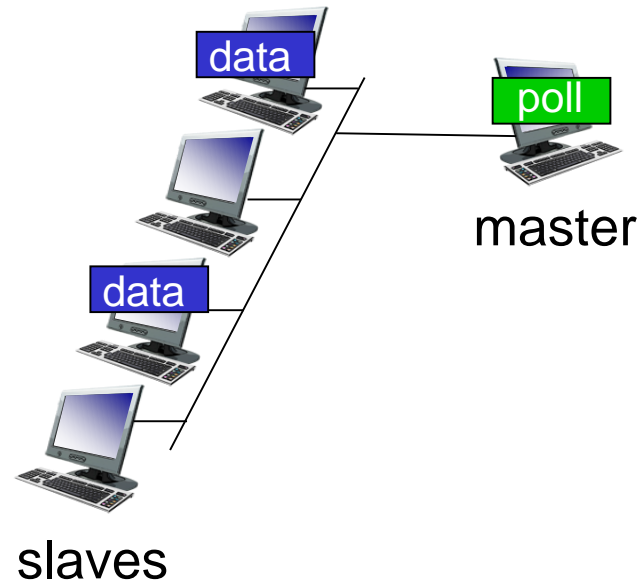
“taking turns” protocols

look for best of both worlds!

“Taking turns” MAC protocols

polling:

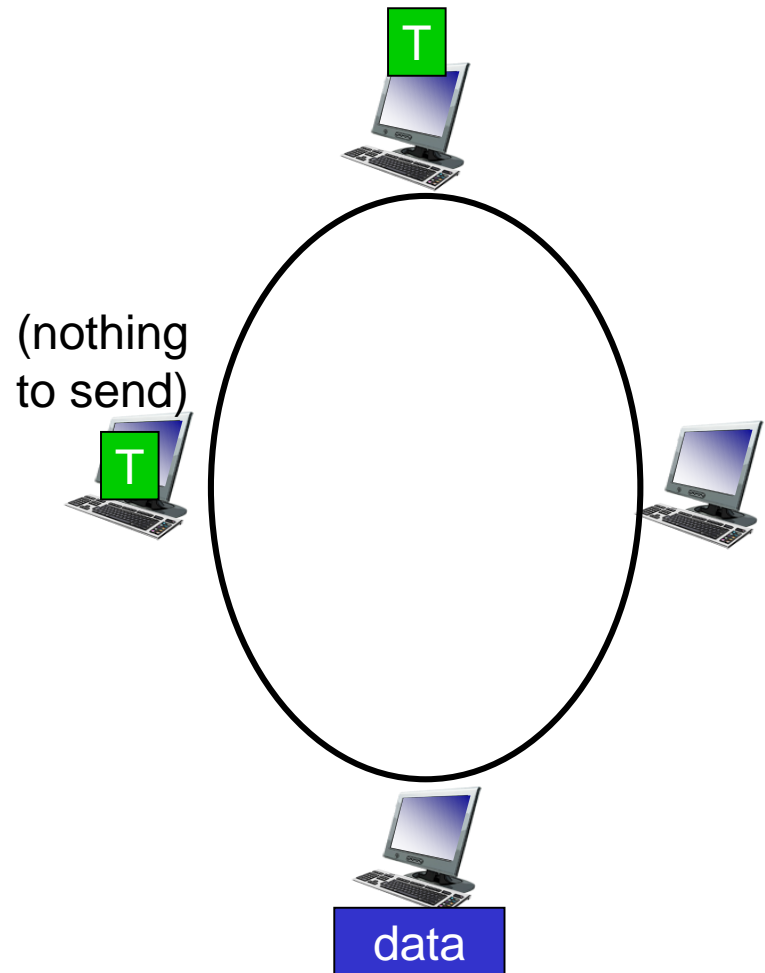
- ❖ master node “invites” slave nodes to transmit in turn
- ❖ typically used with “dumb” slave devices
- ❖ concerns:
 - polling overhead
 - latency
 - single point of failure (master)



“Taking turns” MAC protocols

token passing:

- ❖ control *token* passed from one node to next sequentially.
- ❖ token message
- ❖ concerns:
 - token overhead
 - latency
 - single point of failure (token)



Summary of MAC protocols

- ❖ *channel partitioning*, by time, frequency or code
 - Time Division, Frequency Division
- ❖ *random access* (dynamic),
 - ALOHA, S-ALOHA, CSMA, CSMA/CD
 - carrier sensing: easy in some technologies (wire), hard in others (wireless)
 - CSMA/CD used in Ethernet
 - CSMA/CA used in 802.11
- ❖ *taking turns*
 - polling from central site, token passing
 - bluetooth, FDDI, token ring

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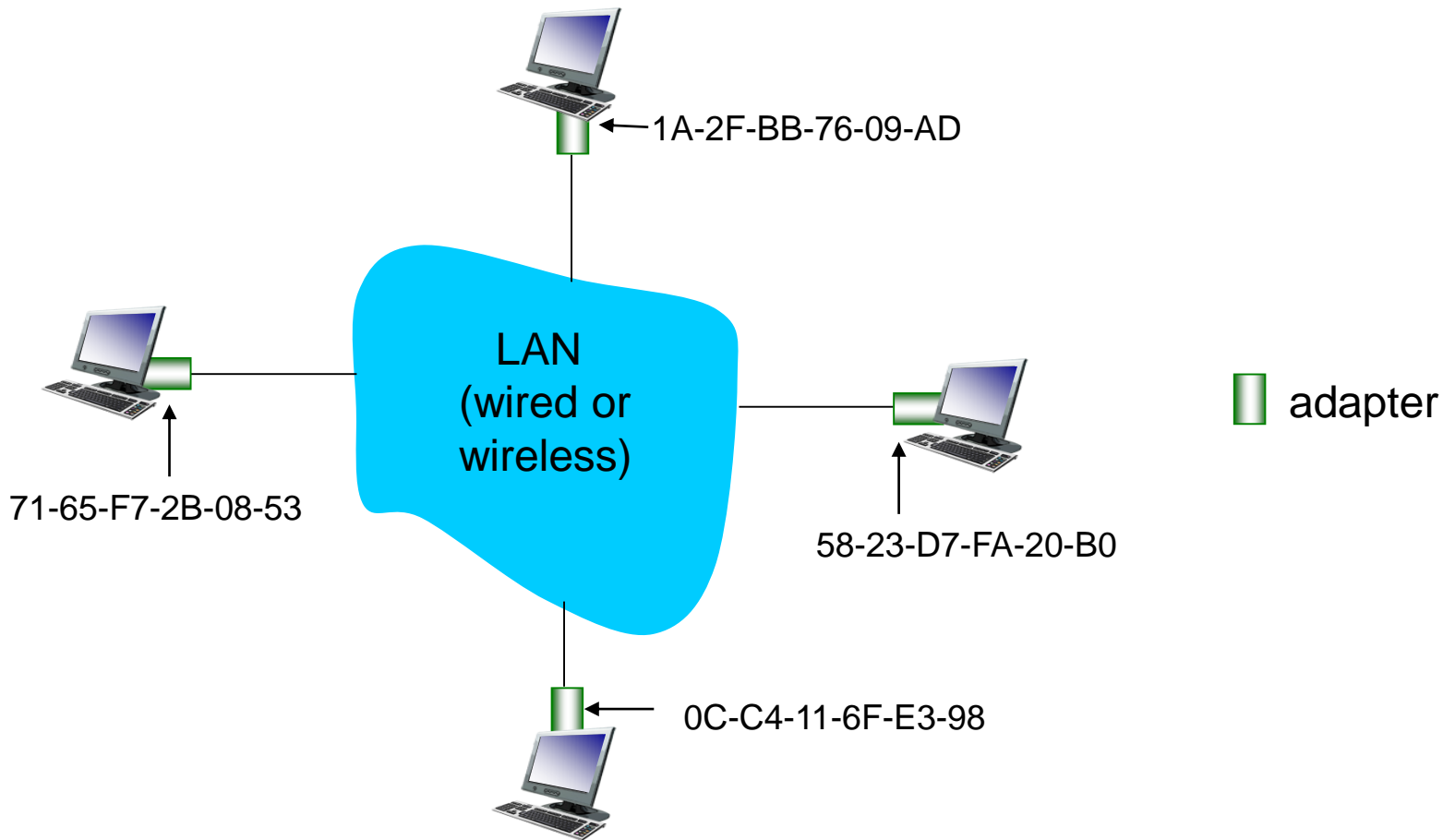
MAC addresses and ARP

- ❖ 32-bit IP address:
 - *network-layer* address for interface
 - used for layer 3 (network layer) forwarding
- ❖ MAC (or LAN or physical or Ethernet) address:
 - function: *used ‘locally’ to get frame from one interface to another physically-connected interface (same network, in IP-addressing sense)*
 - 48 bit MAC address (for most LANs) burned in NIC ROM, also sometimes software settable
 - e.g.: 1A-2F-BB-76-09-AD

hexadecimal (base 16) notation
(each “number” represents 4 bits)

LAN addresses and ARP

each adapter on LAN has unique *LAN* address

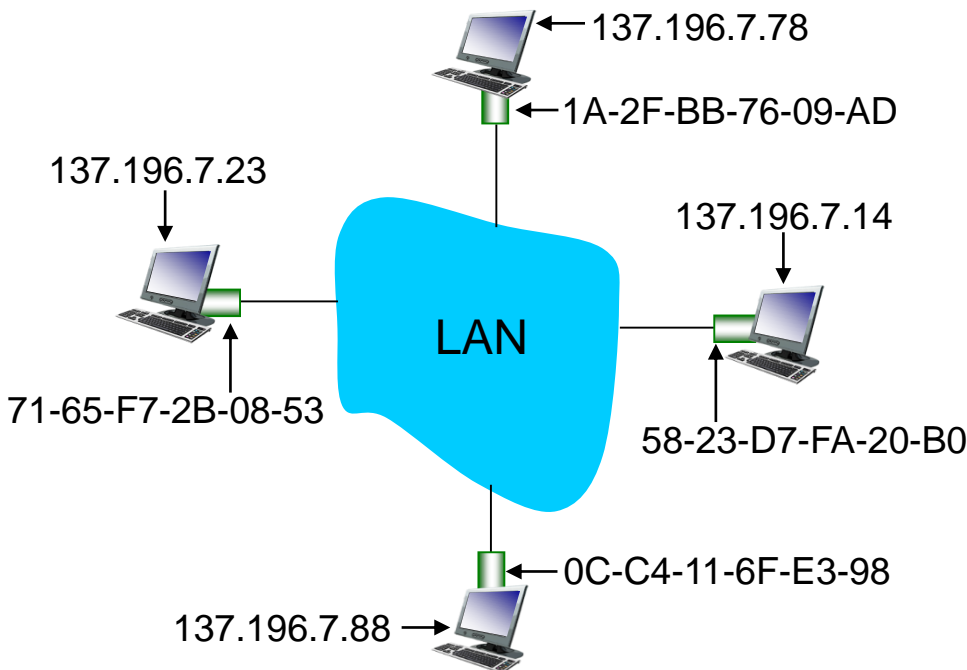


LAN addresses (more)

- ❖ MAC address allocation administered by IEEE
- ❖ manufacturer buys portion of MAC address space (to assure uniqueness)
- ❖ analogy:
 - MAC address: like Social Security Number
 - IP address: like postal address
- ❖ MAC flat address → portability
 - can move LAN card from one LAN to another
- ❖ IP hierarchical address *not* portable
 - address depends on IP subnet to which node is attached

ARP: address resolution protocol

Question: how to determine interface's MAC address, knowing its IP address?



ARP table: each IP node (host, router) on LAN has table

- IP/MAC address mappings for some LAN nodes:
< IP address; MAC address; TTL >
- TTL (Time To Live): time after which address mapping will be forgotten (typically 20 min)

Data center networks

- ❖ 10's to 100's of thousands of hosts, often closely coupled, in close proximity:
 - e-business (e.g. Amazon)
 - content-servers (e.g., YouTube, Akamai, Apple, Microsoft)
 - search engines, data mining (e.g., Google)
- ❖ challenges:
 - multiple applications, each serving massive numbers of clients
 - managing/balancing load, avoiding processing, networking, data bottlenecks



Inside a 40-ft Microsoft container,
Chicago data center