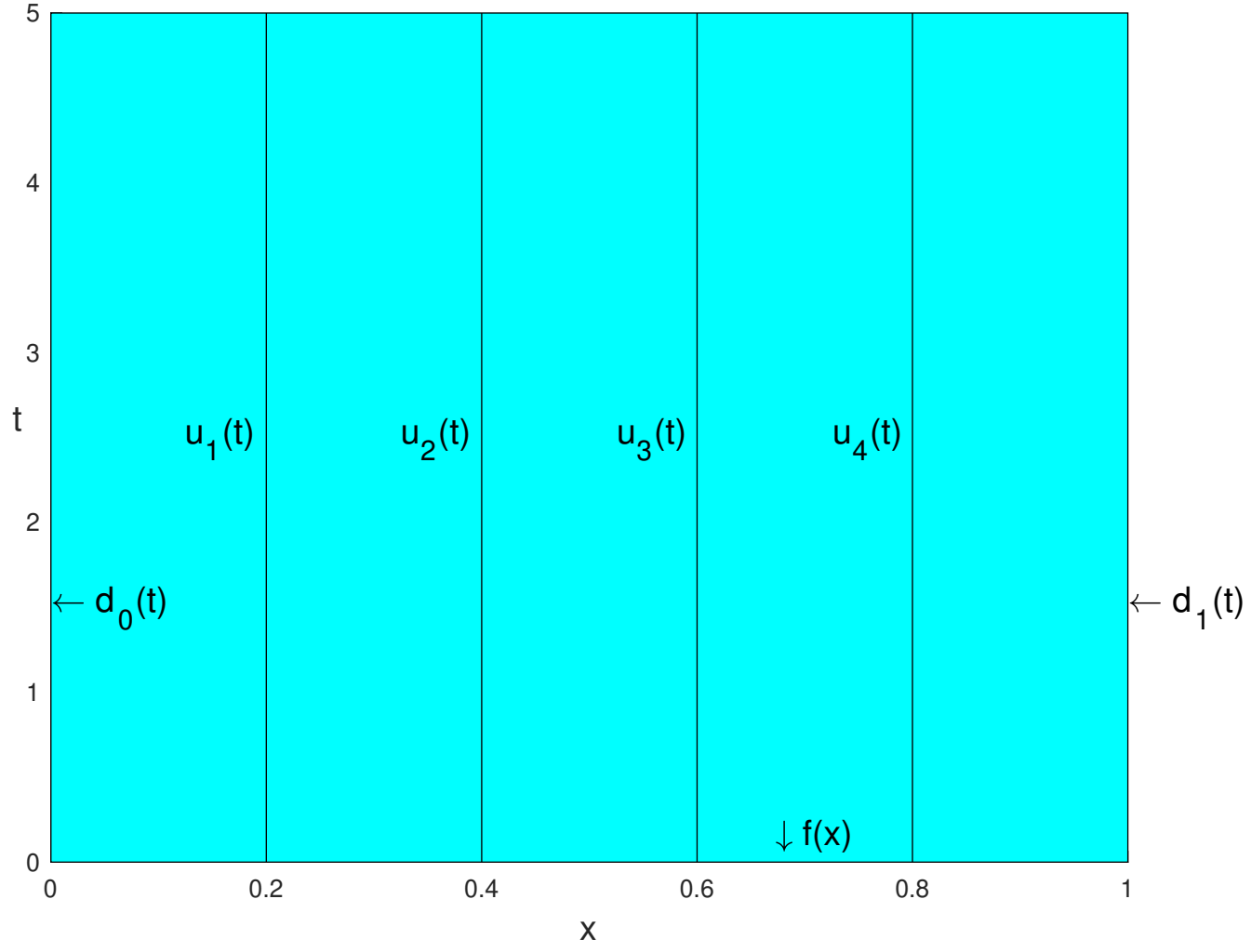
5
4
3
2
1
0
t
0
0.2
0.4
0.6
0.8
1
x
u1(t)
u2(t)
u3(t)
u4(t)
← d0(t)
← d1(t)
↓ f(x)