# A tableau-based decision procedure for a branching-time interval temporal logic 

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## Outline

(1) Introduction
(2) A branching-time interval temporal logic
(3) A Tableau for BTNL[R] $]^{-}$
(4) Future work

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## Interval temporal logics

Interval temporal logics (HS, CDT, PITL) are very expressive

- simple syntax and semantics;
- can naturally express statements that refer to time intervals and continuous processes;
- the most expressive ones (HS and CDT) are strictly more expressive than every point-based temporal logic.

Interval temporal logics are (highly) undecidable
The validity problem for HS is not recursively axiomatizable.

## Problem

Find expressive, but decidable, fragments of interval temporal logics.

## Halpern and Shoam's HS

## HS features four basic unary operators:

- $\langle B\rangle$ (begins) and $\langle E\rangle$ (ends), and their transposes $\langle\bar{B}\rangle$ (begun by) and $\langle\bar{E}\rangle$ (ended by).

- Given a formula $\varphi$ and an interval $\left[d_{0}, d_{1}\right],\langle B\rangle \varphi$ holds over [ $d_{0}, d_{1}$ ] if $\varphi$ holds over [ $d_{0}, d_{2}$ ], for some $d_{0} \leq d_{2}<d_{1}$, and $\langle E\rangle \varphi$ holds over $\left[d_{0}, d_{1}\right]$ if $\varphi$ holds over $\left[d_{2}, d_{1}\right]$, for some $d_{0}<d_{2} \leq d_{1}$.


## Some interesting fragments of HS

- The $\langle B\rangle\langle E\rangle$ fragment (undecidable);
- The $\langle B\rangle\langle\bar{B}\rangle$ and $\langle E\rangle\langle\bar{E}\rangle$ fragments (decidable);
- Goranko, Montanari, and Sciavicco's PNL:
- based on the derived neighborhood operators $\langle\boldsymbol{A}\rangle$ (meets) and $\langle\bar{A}\rangle$ (met by);

- decidable (by reduction to $2 \mathrm{FO}[<]$ ), but no tableau methods.


## The linear case: Right PNL (RPNL)

- future-only fragment of PNL;
- interpreted over natural numbers;
- decidable, doubly exponential tableau-based decision procedure for RPNL (TABLEAUX 2005);
- recently, we devised an optimal (NEXPTIME) tableau-based decision procedure for RPNL.


## The branching case

We developed a branching-time propositional interval temporal logic.

- Such a logic combines:
- interval quantifiers $\langle\boldsymbol{A}\rangle$ and $[A]$ from RPNL;
- path quantifiers $A$ and $E$ from CTL.
- We devised a tableau-based decision procedure for it, combining:
- the tableau for RPNL (TABLEAUX 2005);
- Emerson and Halpern's tableau for CTL (J. of Computer and System Sciences, 1985).


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## Branching Time Right-Neighborhood Logic

## Syntax of BTNL[R] ${ }^{-}$

$$
\varphi=p|\neg \varphi| \varphi \vee \varphi|E\langle A\rangle \varphi| E[A] \varphi|A\langle A\rangle \varphi| A[A] \varphi .
$$

- Interpreted over infinite trees.
- Combines path quantifiers $A$ (for all paths) and $E$ (for any path) with the interval modalities $\langle A\rangle$ and $[A]$.


## BTNL[R]- semantics: $E\langle A\rangle \psi$


$E\langle A\rangle \psi$ holds over $\left[d_{0}, d_{1}\right]$ if $\psi$ holds over $\left[d_{1}, d_{2}\right]$, for some $d_{2}<d_{1}$.

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$E[A] \psi$ holds over $\left[d_{0}, d_{1}\right]$ if there exists an infinite path $d_{1}, d_{2}, \ldots$ such that $\psi$ holds over $\left[d_{1}, d_{i}\right]$, for all $d_{i}>d_{1}$ in the path.

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## BTNL[R]- semantics: A[A] $\psi$


$A[A]$ is the dual of $E\langle A\rangle: A[A] \psi$ holds over [ $\left.d_{0}, d_{1}\right]$ if $\psi$ holds over $\left[d_{1}, d_{2}\right]$, for all $d_{2}<d_{1}$.

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$A\langle A\rangle$ is the dual of $E[A]: A\langle A\rangle \psi$ holds over $\left[d_{0}, d_{1}\right]$ if, for all infinite paths $d_{1}, d_{2}, \ldots, \psi$ holds over $\left[d_{1}, d_{i}\right]$, for some $d_{i}>d_{1}$ in the path.

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## BTNL[R] ${ }^{-}$semantics: $A\langle A\rangle \psi$


$A\langle A\rangle$ is the dual of $E[A]: A\langle A\rangle \psi$ holds over $\left[d_{0}, d_{1}\right]$ if, for all infinite paths $d_{1}, d_{2}, \ldots, \psi$ holds over $\left[d_{1}, d_{i}\right]$, for some $d_{i}>d_{1}$ in the path.

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## Basic blocks

## Definition

An atom is a pair $(\mathcal{A}, \mathcal{C})$ such that:

- $\mathcal{C}$ is a maximal, locally consistent set of subformulae of $\varphi$;
- $\mathcal{A}$ is a consistent (but not necessarily complete) set of temporal formulae $(\boldsymbol{A}\langle\boldsymbol{A}\rangle \psi, \boldsymbol{A}[\boldsymbol{A}] \psi, E\langle\boldsymbol{A}\rangle \psi$, and $E[A] \psi)$;
- $\mathcal{A}$ and $\mathcal{C}$ must be coherent:
if $A[A] \psi \in \mathcal{A}$, then $\psi \in \mathcal{C}$;
if $E[A] \psi \in \mathcal{A}$, then $\psi \in \mathcal{C}$.


## Atoms and Intervals

- Associate with every interval $\left[d_{i}, d_{j}\right]$ an atom $(\mathcal{A}, \mathcal{C})$ :
- $\mathcal{C}$ contains the formulae that (should) hold over $\left[d_{i}, d_{j}\right]$; $\mathcal{A}$ contains temporal requests coming from the past.
- Connect every pair of atoms that are associated with neighbor intervals.


## Tableau nodes

## Definition

A node $N$ of the tableau is a set of atoms such that, for every temporal formula $\psi$ and every pair of atoms $(\mathcal{A}, \mathcal{C}),\left(\mathcal{A}^{\prime}, \mathcal{C}^{\prime}\right) \in N, \psi \in \mathcal{C}$ iff $\psi \in \mathcal{C}^{\prime}$.

## Nodes and points

A node $N$ represents a point $d_{j}$ of the temporal domain:

- every atom in $N$ represents an interval $\left[d_{i}, d_{j}\right]$ ending in $d_{j}$.

A node $N$ representing point $d_{1}$ is an initial node:

- $N$ contains only an atom $(\emptyset, \mathcal{C})$ with $\varphi \in \mathcal{C}$.


## Connecting nodes

We put an edge between two nodes if they represent successive time points:


- $\left(\mathcal{A}_{N}, \mathcal{C}_{N}\right)$ is an atom such that $\mathcal{A}_{N}$ contains all requests (temporal formulae) of $N$;
- for every $(\mathcal{A}, \mathcal{C}) \in N$ representing $\left[d_{i}, d_{j}\right]$ there is $\left(\mathcal{A}^{\prime}, \mathcal{C}^{\prime}\right) \in M_{N}^{\prime}$ representing $\left[d_{i}, d_{j+1}\right]$.


## The decision procedure

(1) Build the (unique) initial tableau $\mathcal{T}_{\varphi}=\left\langle\mathcal{N}_{\varphi}, \mathcal{R}_{\varphi}\right\rangle$.
(2) Delete "useless nodes" by repeatedly applying the following deletion rules, until no more nodes can be deleted:

- delete any node which is not reachable from an initial node;
- delete any node that contains a formula of the form $\boldsymbol{A}[\boldsymbol{A}] \psi, \boldsymbol{A}\langle\boldsymbol{A}\rangle \psi$, $\boldsymbol{E}\langle\boldsymbol{A}\rangle \psi$, or $E[A] \psi$ that is not satisfied.
(3) If the final tableau is not empty, return true, otherwise return false.


## Pruning the tableau: $A[A] \psi$

$A[A]$-formulas are satisfied by construction.

Given a node $N$ and an atom $(\mathcal{A}, \mathcal{C}) \in N$ :

- if $A[A] \psi \in \mathcal{C}$,
- then, for every right neighbor $\left(\mathcal{A}^{\prime}, \mathcal{C}^{\prime}\right), A[A] \psi \in \mathcal{A}^{\prime}$;
- hence, by definition of atom, $\psi \in \mathcal{C}^{\prime}$.


## Pruning the tableau: $A\langle A\rangle \psi$

$A\langle A\rangle$-formulas are checked by a marking procedure.
(1) For all nodes $N$, mark all atoms $(\mathcal{A}, \mathcal{C}) \in N$ such that $A\langle\boldsymbol{A}\rangle \psi \in \mathcal{A}$ and $\psi \in \mathcal{C}$.
(2) For all nodes $N$, mark all unmarked atoms $(\mathcal{A}, \mathcal{C}) \in N$ such that there exists a successor $M$ of $N$ that contains a marked atom $\left(\mathcal{A}^{\prime}, \mathcal{C}^{\prime}\right)$ that is a right neighbor of $(\mathcal{A}, \mathcal{C})$.
(3) Repeat this last step until no more atoms can be marked.
(4) Delete all nodes that either contain an unmarked atom $(\mathcal{A}, \mathcal{C})$ with $A\langle A\rangle \psi \in \mathcal{A}$ or have no successors.

## Pruning the tableau: $E\langle A\rangle \psi$

$E\langle A\rangle$-formulas are checked by searching for a descendant.

Given a node $N$ and an atom $(\mathcal{A}, \mathcal{C}) \in N$, if $E\langle A\rangle \psi \in \mathcal{C}$, search for a descendant $M$ such that:
(1) $M$ contains an atom $\left(\mathcal{A}^{\prime}, \mathcal{C}^{\prime}\right)$ that is a right-neighbor of $(\mathcal{A}, \mathcal{C})$;
(2) $\psi \in \mathcal{C}^{\prime}$.

## Pruning the tableau: $E[A] \psi$

$E[A]$-formulas are checked by searching for a loop.

Given a node $N$ and an atom $(\mathcal{A}, \mathcal{C}) \in N$, if $E[A] \psi \in \mathcal{C}$, search for a path leading to a loop such that:

- every node in the path and in the loop contains an atom $\left(\mathcal{A}^{\prime}, \mathcal{C}^{\prime}\right)$ such that:
(1) $\left(\mathcal{A}^{\prime}, \mathcal{C}^{\prime}\right)$ is a right-neighbor of $(\mathcal{A}, \mathcal{C})$;
(2) $\psi \in \mathcal{C}^{\prime}$.


## Building a model for $\varphi$

An infinite model for $\varphi$ can be build by unfolding the final tableau.
(1) Select an initial node $N_{1}$;
(2) finite paths $N_{1} N_{2} \ldots N_{k}$ starting from the initial node becomes the points of the infinite tree;
(3) define the valuation function respecting atoms (this is the key step).

## Computational Complexity

- The size of the tableau is doubly exponential in the length of the formula;
- all checkings of the algorithm can be done in time polynomial in the size of the tableau;
- after deleting at most $\left|\mathcal{N}_{\varphi}\right|$ nodes, the algorithm terminates.

Checking the satisfiability for a BTNL[R] $]^{-}$formula is doubly exponential in the length of $\varphi$.

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## Future work

- Complexity issues:
- we do not know yet whether the satisfiability problem for BTNL[R] ${ }^{-}$ is doubly EXPTIME-complete or not (we conjecture it is not!).
- Extensions:
- to combine path quantifiers operators with other sets of interval logic operators, e.g., those of PNL.

