

Master degree course on Approximation Theory and Applications, Lab exercises

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- Using the **chebfun** <http://www.chebfun.org/examples/approx/BestApprox.html> code, **remez.m**, compute the BPA of $f(x) = x^{k+1}$ on $[-1, 1]$ for $k = 2, 4, 6$. As degree of the polynomial of best approximation take $n \leq k$.

Repeat for the function $f(x) = \sin((2k+1)x)$. What do we see?

```
%-----
function [p,err] = remez(f,n); % compute deg n BA to chebfun f
iter = 1; delta = 1; deltamin = delta;
[a,b] = domain(f);
xk = chebpts(n+2); xo = xk; % initial reference
sigma = (-1).^[0:n+1]; % alternating signs
normf = norm(f);
while (delta/normf > 1e-14) & iter <= 20
    fk = feval(f,xk); % function values
    w = bary_weights(xk); % compute barycentric weights
    h = (w*fk)/(w*sigma); % levelled reference error
    if h==0, h = 1e-19; end % perturb error if necessary
    pk = fk - h*sigma; % polynomial vals in the
    p=chebfun(@(x)bary(x,pk,xk,w),n+1); % reference chebfun of trial
    e = f - p; % polynomial chebfun of the
    [xk,err] = exchange(xk,e,h,2); % error replace reference
    if err/normf > 1e5 % if overshoot, recompute with
    [xk,err] = exchange(xo,e,h,1); % one-point exchange
end
xo = xk;
delta = err - abs(h); % stopping value
if delta < deltamin, % store poly with minimal norm
    deltamin = delta;
pmin = p; errmin = err;
end
iter = iter + 1;
end
p = pmin; err = errmin;
%-----
```

2. Leja sequences

Definition 1. On $[a, b]$ take the point x_1 . The point $x_s \in [a, b]$, $s = 2, 3, \dots, N$ s.t.

$$\prod_{k=1}^{s-1} |x_s - x_k| = \max_{x \in [a, b]} \prod_{k=1}^{s-1} |x - x_k|. \quad (1)$$

is called a Leja sequence for $[a, b]$.

Write a Matlab code that constructs the sequence and then use it for constructing the interpolating polynomial in Newton form of the function $f(x) = \sin(x) + \cos(x)$, $x \in [0, \pi]$.