

Shift optimization for solution of large scale evolutionary problems by means of Galerkin approach on rational Krylov subspaces

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1 Objective:

Economical computation of

$$\exp(-tA)\varphi, \quad t \geq \mathbf{0}, \quad (1)$$

for

$$A^* = A, \quad \mathbf{0} < \lambda_{\min}I \leq A \leq \lambda_{\max}I. \quad (2)$$

This problem is related with computation of

$$(A + i\omega I)^{-1}\varphi, \quad \omega \in \mathbf{R}, \quad (3)$$

via Fourier transform. Both the problems contain a parameter (ω or t).

2 Outline:

1. Galerkin approach on Rational Krylov Subspace. 2. Skeleton approximation. 3. Problem (1–2).

3 Galerkin approach on Rational Krylov Subspace

Rational Krylov subspace (A. Ruhe):

$$U = \mathbf{span}\{(A + s_1 I)^{-1}\varphi, \dots, (A + s_n I)^{-1}\varphi\}, \quad s_j \notin -\mathbf{CoSp} A. \quad (4)$$

Our solution method: Galerkin projection with **good choice of s_j** .

RKSR approximant:

$$f(A)\varphi = u \approx u_n = Gf(V)G^*\varphi, \quad f(\lambda) = (\lambda + i\omega)^{-1}, \quad (5)$$

where the columns of G form an orthonormal basis of U , $V = G^*AG$.

Good approximation with poles $-s_j$ implies a good error estimate:

Proposition 1 *Let p be a polynomial of degree not exceeding $n - 1$. Then the estimate*

$$\|u - u_n\| \leq 2 \max_{\lambda \in \mathbf{CoSp} A} \left| f(\lambda) - \frac{p(\lambda)}{q(\lambda)} \right| \quad (6)$$

takes place with

$$q(\lambda) = \prod_{j=1}^n (\lambda + s_j). \quad (7)$$

Remark 1 *A similar result was independently presented by B. Beckermann and L. Reichel 2008.*

4 Skeleton approximation

Motivation of use: presence of a parameter. Standard RA is not enough. SA was introduced in [Tyrtysnikov96] and exploited in [Goreinov99, HackbuschKhoromskiiTyrtysnikov05]. For the function $\mathbf{1}/(\lambda + s)$ it was investigated in [Oseledets07]. The definition:

$$f_{\text{skel}}(\lambda, s) = \left(\frac{\mathbf{1}}{\lambda + s_1}, \dots, \frac{\mathbf{1}}{\lambda + s_n} \right) M^{-1} \left(\frac{\mathbf{1}}{s + \lambda_1}, \dots, \frac{\mathbf{1}}{s + \lambda_n} \right)^T, \quad (8)$$

where

$$M = (M_{kl}), \quad M_{kl} = \mathbf{1}/(\lambda_k + s_l), \quad \mathbf{1} \leq k, l \leq n. \quad (9)$$

Theorem 3 from [Oseledets07] gives an expression for the relative error:

$$\eta = \left[\frac{\mathbf{1}}{\lambda + s} - f_{\text{skel}}(\lambda, s) \right] / \frac{\mathbf{1}}{\lambda + s} = \prod_{j=1}^n \frac{\lambda - \lambda_j}{\lambda + s_j} \cdot \prod_{j=1}^n \frac{s - s_j}{s + \lambda_j}. \quad (10)$$

A convenient error representation (leading to **Zolotaryov's problem**):

$$\eta(\lambda, s) = \frac{r(\lambda)}{r(-s)}, \quad r(z) = \prod_{j=1}^n \frac{z - \lambda_j}{z + s_j}. \quad (11)$$

Keep in mind: $\lambda \hookrightarrow A$, $s \hookrightarrow i\omega I$.

5 Evolutionary problem

[Quadrature approach: a number of papers by L. N. Trefethen with collaborators; designed for moderate t_{\max}/t_{\min} .]

We use skeleton approximation. Put

$$\epsilon(\lambda, t) \equiv \mathcal{F}_\omega^{-1} \left[\frac{\mathbf{1}}{\lambda + i\omega} - f_{\text{skel}}(\lambda, i\omega) \right] (t) \quad (12)$$

— approximation error for $e^{-t\lambda}$. Plancherel's theorem implies:

Proposition 2 *The approximation error satisfies the inequality*

$$\begin{aligned} & \max_{\lambda \in [\lambda_{\min}, \lambda_{\max}]} \|\epsilon(\lambda, \cdot)\|_{L_2[0, +\infty[} \quad (13) \\ & \leq \pi \sqrt{\frac{2}{\lambda_{\min}}} \max_{\lambda \in [\lambda_{\min}, \lambda_{\max}]} |r(\lambda)| \max_{s \in i\mathbf{R} \cup \{\infty\}} |r(s)|^{-1}. \end{aligned}$$

Parameter optimization: **the third Zolotaryov problem** with the condenser (E, D) whose compact (in $\overline{\mathbf{C}}$) plates are

$$E = [\lambda_{\min}, \lambda_{\max}] \quad \text{and} \quad D = \{z \in \mathbf{C} \mid \Re z \leq \mathbf{0}\}. \quad (14)$$

Introduce the quantity

$$\sigma_n(E, D) = \min_{\lambda_1, \dots, \lambda_n, s_1, \dots, s_n} \frac{\max_{\lambda \in [\lambda_{\min}, \lambda_{\max}]} |r(\lambda)|}{\min_{s \in i\mathbf{R} \cup \{\infty\}} |r(s)|}; \quad (15)$$

$$\delta = \lambda_{\min}/\lambda_{\max}, \quad \mu = \left(\frac{1 - \sqrt{\delta}}{1 + \sqrt{\delta}} \right)^2, \quad (16)$$

$$\rho = \exp \left(-\frac{\pi}{4} \cdot \frac{K'(\mu)}{K(\mu)} \right) \stackrel{\text{large } \lambda_{\max}/\lambda_{\min}}{\approx} \exp \left(-\frac{\pi^2}{2} / \log \frac{4\lambda_{\max}}{\lambda_{\min}} \right). \quad (17)$$

Theorem 1 *The assertion*

$$\rho^n \leq \sigma_n(E, D) \leq 2\rho^n \quad (18)$$

holds.

The lower bound: computation of the Riemann modulus of the condenser (E, D) and application of Gonchar's theorem from [Gonchar69]. The upper bound is provided with the parameter set obtained by means of minimization under the additional condition $s_j = \lambda_j$:

$$s_j = \lambda_j = \lambda_{\max} \mathbf{dn} \left(\frac{2(n-j)+1}{2n} K'(\delta), \sqrt{1-\delta^2} \right), \quad j = 1, \dots, n. \quad (19)$$

It was shown in [BaillyThiran00] that (19) satisfy some local optimality condition.

Remark 2 *All the parameters in (19) are real which enables us to exploit real arithmetic in industrial Fortran programs.*

Remark 3 *If we take (again real) infinite sequence of parameters $s_j = \lambda_j$, having the same limit (as $n \rightarrow \infty$) distribution as in (19), we shall obtain the same asymptotical (in the Cauchy–Hadamard sense) convergence factor ρ . This allows us to extend the parameter set when moving from n to $n + 1$ (in the style of [Gonchar78, SaffTotik97, Leja57, BaglamaCalvettiReichel98]).*

Remark 4 *Adaptive change of parameters: a work by D and Z under preparation.*

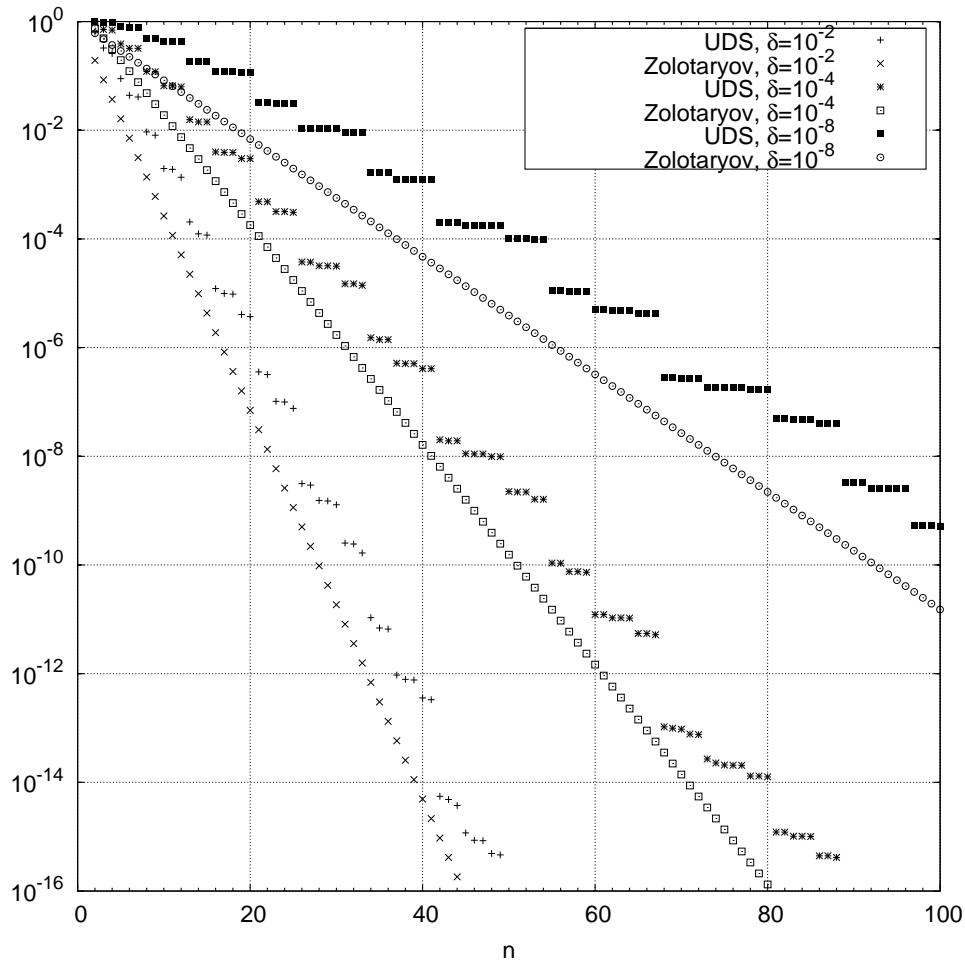


Figure 1: Comparison of Zolotaryov fractions with ones based on uniformly distributed sequences (UDS). The error $\max_{z \in [\lambda_{\min}, \lambda_{\max}]} \left| \prod_{l=1}^n \frac{z - s_l}{z + s_l} \right|$ as a function of n for the two families of parameter sets; $\lambda_{\min} = 10^{-4}$, $\lambda_{\max} = \mathbf{1}$; three values of $\delta = \lambda_{\min}/\lambda_{\max}$.

Numerical experiments. Maxwell's system. Comparison with the version of the Restricted Denominator Method from [vdEshofHochbruck06] designed for a particular t (parameter choice from [Andersson81]).

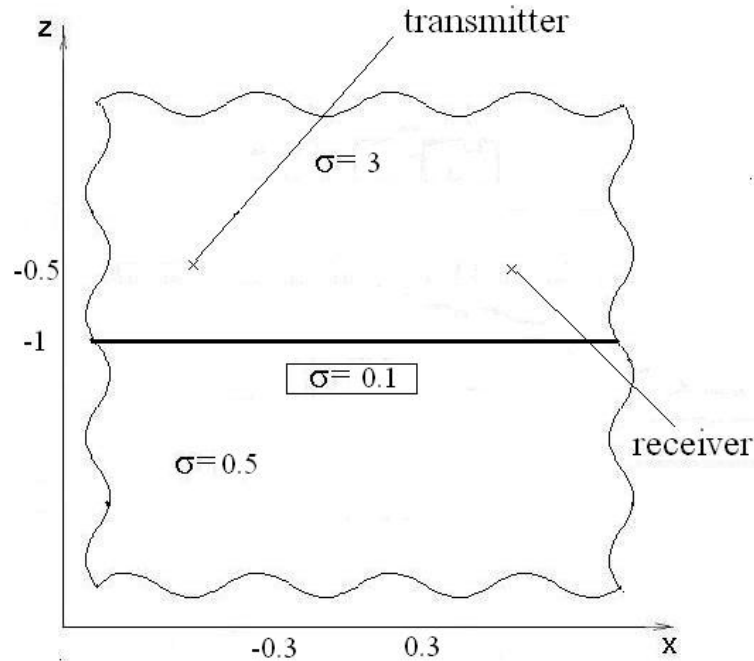


Figure 2: Model medium.

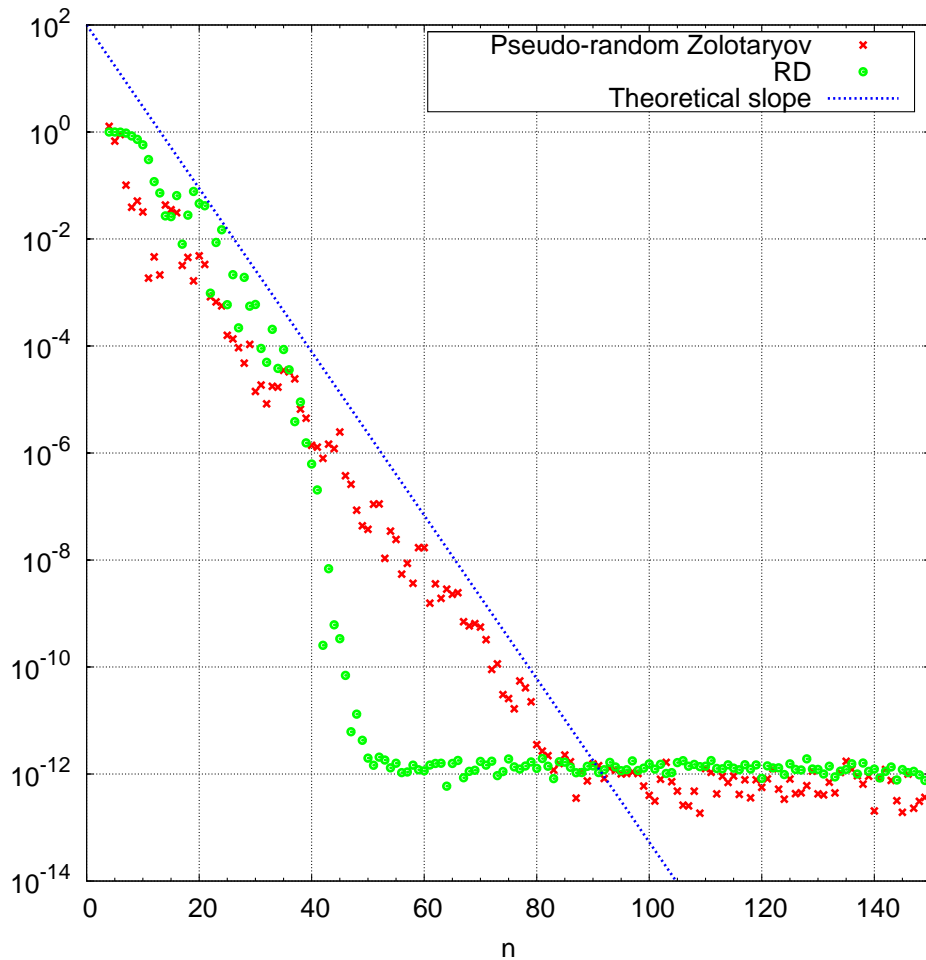


Figure 3: $t = 1$. RD approach converges significantly faster than our approach.

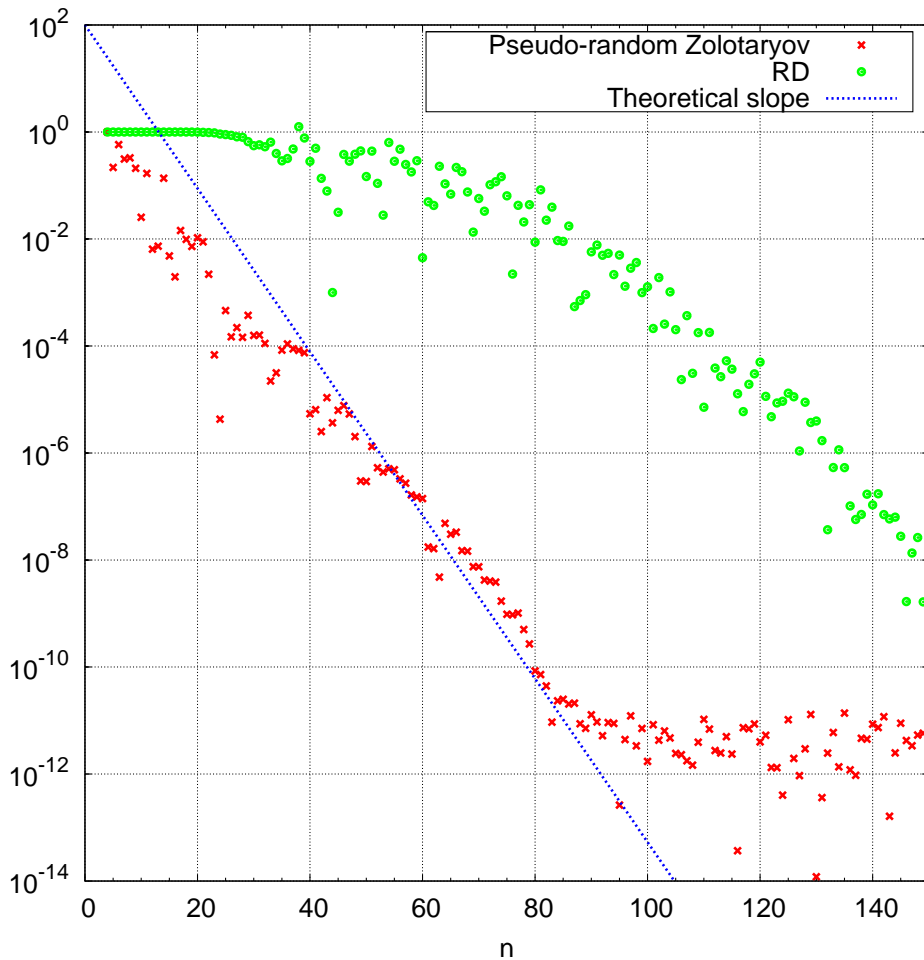


Figure 4: $t = \mathbf{10}$. Our approach becomes favorable for values of t not close to the one RD approach is targeted to.

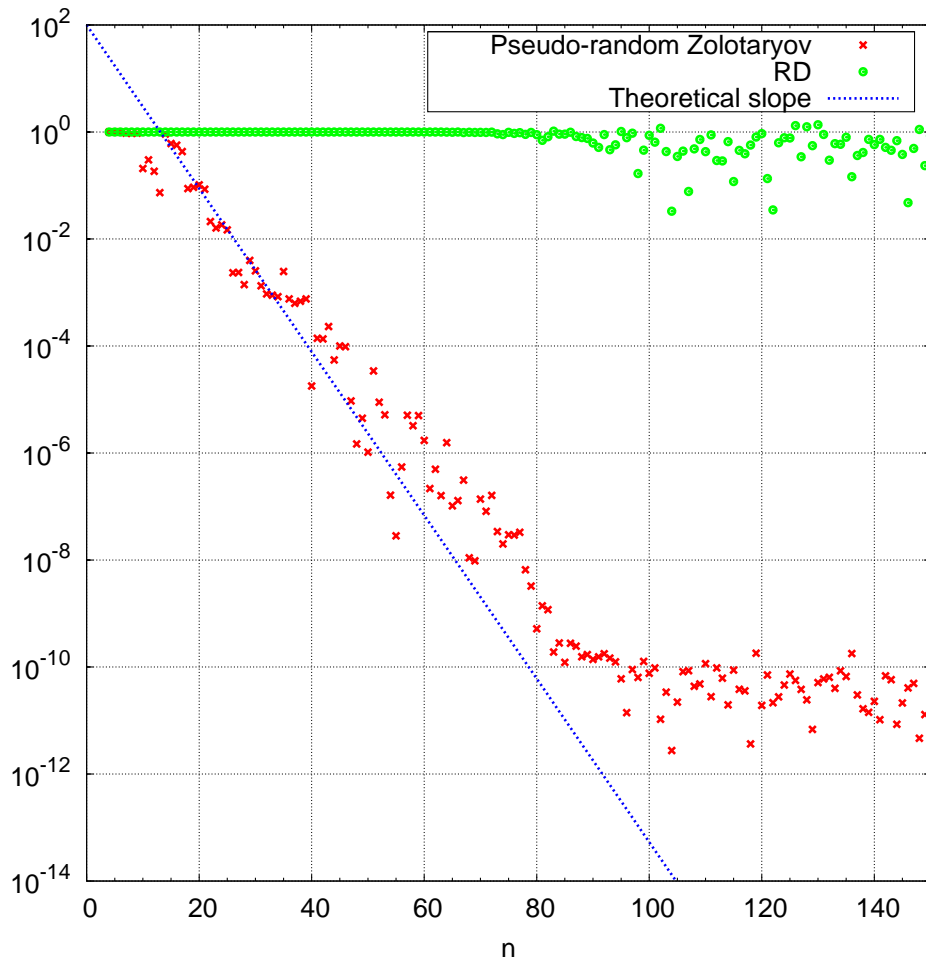


Figure 5: $t = \mathbf{100}$. RD approach almost stops converging while our approach shows almost the same convergence rate as for $t = \mathbf{1}$ and $t = \mathbf{10}$.

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