

## FUNDAMENTAL SOLUTION

Our goal is to find a special solution for the equation

$$-\Delta u = 0$$

in a subset of  $\mathbb{R}^n$  (precisely in  $\mathbb{R}^n \setminus \{0\}$ )

This function will be called fundamental solution.

It will be clear later why the name "fundamental".

First we see a general fact.

FACT - The equation  $\Delta u = 0$  is rotations invariant, that is if

$$\Delta u(x) = 0 \quad \forall x \in \mathbb{R}^n \quad \text{then}$$

$$\Delta v(x) = 0 \quad \forall x \in \mathbb{R}^n \quad \text{where } v(y) = u(\pi y)$$

where  $\pi$  is a unitary matrix

proof: let  $\pi$  be an invertible matrix such that

$$\pi^{-1} = \pi^t \quad \text{and write } x = \pi y$$

Now define  $v(y) := u(\pi y)$  where  $\Delta u(x) = 0$   
 $\forall x \in \mathbb{R}^n$

$$\frac{\partial v}{\partial y_i}(y) = \frac{\partial}{\partial y_i} (u(\pi_1 \cdot y, \dots, \pi_n \cdot y)) =$$

$$\left( \pi_k \cdot y = m_{k1} y_1 + \dots + m_{kn} y_n \right)$$

$$= \sum_{k=1}^n \frac{\partial u}{\partial x_k}(\pi y) m_{ki}$$

$$\frac{\partial^2 v}{\partial y_i^2}(y) = \sum_{h,k=1}^n \frac{\partial^2 u}{\partial x_h \partial x_k}(\pi y) m_{ki} m_{hi}$$

$$m_{hi} = (\pi^{-1})_{ih}$$

$$\begin{aligned} \Delta v(y) &= \sum_{i=1}^n \frac{\partial^2 v}{\partial y_i^2}(y) = \sum_{h,k=1}^n \frac{\partial^2 u}{\partial x_h \partial x_k}(\pi y) \underbrace{\sum_{i=1}^n \pi_{ki} (\pi^{-1})_{ih}}_{= \delta_{kh}} \\ &= \sum_{k=1}^n \frac{\partial^2 u}{\partial x_k^2}(\pi y) = \\ &= \Delta u(\pi y) = 0 \end{aligned}$$

This in particular means that if  $u$  is harmonic  
 and  $\pi$  is a rotation (which is unitary)

then  $v$  is harmonic, where  $v(y) := u(|y|)$ .

This in particular holds if  $u$  is radial.

! This does not mean that the solutions of  
-  $\Delta u = 0$  are (all) radial

## HARMONIC FUNCTIONS AND HOLOMORPHIC FUNCTIONS

In fact, in  $n=2$  for instance, the theory of harmonic functions is connected with the holomorphic functions  $f: \mathbb{C} \rightarrow \mathbb{C}$ .

Consider  $u$  and  $v$  respectively the real and the imaginary part of  $f$  (holomorphic), i.e.

$$f(z) = u(x,y) + i v(x,y) \quad \bar{z} = x + iy \quad u, v: \mathbb{R}^2 \rightarrow \mathbb{R}$$

Computing the derivative of  $f$  in  $z_0 = (x_0, y_0)$  we have

$$\lim_{\substack{h, k \rightarrow 0 \\ (h, k) \neq (0,0)}} \frac{f(z_0 + h + ik) - f(z_0)}{h + ik} = f'(z_0)$$

$$\begin{aligned} k=0 \quad \lim_{h \rightarrow 0} \frac{u(x_0 + h, y_0) + i v(x_0 + h, y_0) - u(x_0, y_0) - i v(x_0, y_0)}{h} \\ = \frac{\partial u}{\partial x}(x_0, y_0) + i \frac{\partial v}{\partial x}(x_0, y_0) = f'(z_0) \end{aligned}$$

$$h=0 \quad \dots \quad f'(z_0) = \frac{1}{i} \frac{\partial u}{\partial y}(x_0, y_0) + \frac{\partial v}{\partial y}(x_0, y_0)$$

$$\text{Then} \quad u_x + i v_y = v_y + \frac{1}{i} u_y \quad \Rightarrow \quad \left| \begin{array}{l} u_x = v_y \\ u_y = -v_x \end{array} \right.$$

$$\Rightarrow \text{(since } u \text{ and } v \in C^\infty) \quad \begin{aligned} u_{xx} + v_{yy} &= 0 \\ v_{xx} + u_{yy} &= 0 \end{aligned}$$

That is : the real and imaginary part of a holomorphic function  $f$  are harmonic

For example, the functions  $f(z) = z^m$  ( $m \in \mathbb{N}$ ) and  $g(z) = e^{ixz}$  are holomorphic in  $\mathbb{C}$ .

Writing  $z = x + iy$  one gets

$$m = 0 \quad u(x, y) = 1$$

$$m = 1 \quad x + iy \quad u(x, y) = x \quad v(x, y) = y$$

$$m = 2 \quad (x + iy)^2 = x^2 - y^2 + 2ixy$$

$$u(x, y) = x^2 - y^2 \quad v(x, y) = 2xy$$

$$m = 3 \quad (x + iy)^3 = x^3 + 3ix^2y - 3xy^2 + i^3y^3$$

$$\vdots \quad u(x, y) = x^3 - 3xy^2$$

$$\vdots \quad v(x, y) = 3x^2y - y^3$$

$$\text{or} \quad u(x, y) = e^{\alpha x} \cos \alpha y, \quad v(x, y) = e^{\alpha x} \sin \alpha y.$$

Notice that taking  $h(z) = \log z$

we derive that

$$u(x,y) = \log |z| = \log \rho = \log \sqrt{x^2 + y^2}$$

is harmonic in  $\mathbb{R}^2 \setminus \{(0,0)\}$

and  $v(x,y) = \theta$  harmonic in  $\mathbb{R}^2 \setminus S$

$S$  half-line starting in  $(0,0)$

Therefore we have a lot (infinite) non-radial harmonic functions.

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More generally, without writing the Laplacian in new coordinates, we look for a radial solution to

$$-\Delta u = 0 \quad \text{in } \mathbb{R}^n \quad (\text{in } \mathbb{R}^n \setminus \{0\})$$

for every  $n \geq 2$ , i.e. we look for a solution  $u$  such that  $u(x) = v(|x|)$  for some  $v$

$$|x| = \sqrt{x_1^2 + \dots + x_n^2} =: r(x)$$

$$\frac{\partial r}{\partial x_i} = \frac{1}{2|x|} \cdot 2x_i = \frac{x_i}{|x|} \quad \text{and then}$$

$$\frac{\partial u}{\partial x_i}(x) = \frac{dv}{dr}(r(x)) \frac{x_i}{|x|}$$

$$\begin{aligned} \frac{\partial^2 u}{\partial x_i^2}(x) &= \frac{d^2 v}{dr^2}(r(x)) \frac{x_i^2}{|x|^2} + \frac{dv}{dr}(r(x)) \frac{\partial}{\partial x_i} \left( \frac{x_i}{|x|} \right) = \\ &= v''(r) \frac{x_i^2}{|x|^2} + v'(r) \frac{|x|^2 - x_i^2}{|x|^3} \end{aligned}$$

$$\begin{aligned} \Rightarrow \Delta u(x) &= \frac{v''(\kappa)}{\kappa^2} \sum_{i=1}^n x_i^2 + \frac{v'(\kappa)}{\kappa^3} (n-1)\kappa^2 \\ &= v''(\kappa) + \frac{(n-1)}{\kappa} v'(\kappa) = 0 \end{aligned}$$

Notice that for  $n=2$  we get the equation obtained before when we explicitly wrote the Laplacian.

RECALL To solve  $y' + ay = 0$  one has to compute one primitive of  $a$ ,  $A(t) = \int a(t) dt$ , and then a generic solution will be  $y(t) = c e^{-\int a(t) dt}$

Then

$$v''(\kappa) + \frac{(n-1)}{\kappa} v'(\kappa) = 0$$

$$w'(\kappa) + \frac{n-1}{\kappa} w(\kappa) = 0$$

$$\int \frac{1}{\kappa} d\kappa = \log|\kappa| + \kappa \quad (\kappa > 0) \quad \text{and choose } \kappa = 0$$

Then

$$w(r) = a e^{-(m-1) \log r} = a \frac{1}{r^{m-1}}, \quad a \in \mathbb{R}$$

and finally ( $v' = w$ )

$$v(r) = \begin{cases} a \log r + b & \text{if } m=2 \\ \frac{a}{2-m} r^{2-m} + b & \text{if } m \geq 3 \end{cases}$$

$a, b \in \mathbb{R}$

We define

$$F(x) = \begin{cases} -\frac{1}{2u} \log |x| & \text{if } m=2 \\ \frac{1}{(m-2)|S^{m-1}|} \frac{1}{|x|^{m-2}} & \text{if } m \geq 3 \end{cases}$$

$$S^{m-1} = \{x \in \mathbb{R}^m \mid |x| = 1\}$$

**EX** Verify that  $F$  and  $\nabla F \in L^1_{loc}(\mathbb{R}^m)$ .

Curiosity Denote by  $\sigma_n$  the quantity  $|S^{n-1}|$   
and by  $\omega_n$  " " "  $|B_1|$

$$\left( |S^{n-1}| := |S^{n-1}|_{\mathbb{H}^{n-1}}, \quad |B_1| := |B_1(0)|_{\mathbb{L}^n}, \right.$$

being  $\mathbb{H}^{n-1}$  the  $(n-1)$ -dimensional Hausdorff measure,  
 $\mathbb{L}^n$  the  $n$ -dimensional Lebesgue measure )

Given  $r > 0$  and  $B_r \subseteq \mathbb{R}^n$  one then has

$$|B_r| = \omega_n r^n \quad \text{and} \quad |\partial B_r| = \sigma_n r^{n-1}.$$

Then

$$|\partial B_r| = \frac{d}{dr} |B_r|$$

and in particular  $\sigma_n = n \omega_n$ .

proof (EX)

Use the formula

See, e.g., EVANS PDE  
Appendix C

$$\int_{B_r(x_0)} f(x) dx = \int_0^r dr \int_{\partial B_r(x_0)} f d\mathbb{H}^{n-1}$$

that holds for every  $f \in C^0(\overline{B_r(x_0)})$

and take  $f \equiv 1$ .

The remark made at the beginning, i.e.  $\Delta u = 0$  even with a rotation of coordinates, justifies the research of a radial solution in dimension  $n$ .

Prob Suppose you want to solve, for some  $f$ ,

$$P(D)u = f$$

$P(D)$  is a differential polynomial of degree  $N$  and  $f \in C_c^\infty(\mathbb{R}^n)$  (it would be sufficient  $f \in C_c^N$ )

( $P$  is a polynomial in the  $n$  variables  $x_1, \dots, x_n$  and  $D$  is  $(D_1, \dots, D_n) = (\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n})$ )

Suppose there exists a function  $E$  such that

$$P(D)E = \delta \quad (\text{Dirac delta in the origin})$$

in the sense of distributions.

Consider the function  $E * f$  and observe that

$$\begin{aligned} P(D)(E * f) &= (P(D)E) * f = \\ &= \delta * f = f \end{aligned}$$

Def  $E$  is said fundamental solution for the differential operator  $P(D)$ .

The interest to find the fundamental solution is clear:  
once one knows  $E$  one can solve (theoretically)

$$P(D)u = f \quad \text{whatever } f \in \mathcal{D}(\mathbb{R}^n)$$

simply taking  $E * f$ .

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Now, which is the meaning of  $P(D)u = \delta$  for  
some  $u \in L^1_{loc}(\mathbb{R}^n)$ ?

We have seen that a distribution  $T$  is  
infinitely differentiable and  $D^\alpha T$  is the distribution  
acting as follows

$$\langle D^\alpha T, \phi \rangle \stackrel{\text{def}}{=} (-1)^{|\alpha|} \langle T, D^\alpha \phi \rangle_{\mathcal{D}' \times \mathcal{D}} \quad \forall \phi \in \mathcal{D}(\Omega)$$

In particular we are now interested in the solutions  
of  $-\Delta u = \delta$ .

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Def (distributional solutions)

We will say that a function  $u \in L^1_{loc}(\mathbb{R}^n)$   
verifies the equation

$$-\Delta u = \tau \quad \text{for some } \tau \in \mathcal{D}'(\mathbb{R}^n)$$

in the distributional sense  $\Leftrightarrow$  for every  $\phi \in \mathcal{D}(\mathbb{R}^n)$

$$-\int_{\mathbb{R}^n} u(x) \Delta \phi(x) dx = \langle \tau, \phi \rangle_{\mathcal{D}' \times \mathcal{D}} \quad \forall \phi \in \mathcal{D}(\mathbb{R}^n).$$

In particular

$$\underline{-\Delta u = \delta \quad \text{in the distributional sense}}$$

$\Leftrightarrow$

$$-\int_{\mathbb{R}^n} u(x) \Delta \phi(x) dx = \phi(0) \quad \forall \phi \in \mathcal{D}(\mathbb{R}^n).$$

and  $u$  is harmonic in the distributional sense

$\Leftrightarrow$

$$-\int_{\mathbb{R}^n} u(x) \Delta \phi(x) dx = 0 \quad \forall \phi \in \mathcal{D}(\mathbb{R}^n).$$

If we know that  $u, \nabla u \in L^1_{loc}(\mathbb{R}^n)$  then

$$-\int_{\mathbb{R}^n} u \Delta \phi dx = \int_{\mathbb{R}^n} \nabla u \cdot \nabla \phi dx.$$

Now we verify that  $E(x,y) = -\frac{1}{2v} \log |(x,y)|$   
 is the fundamental solution for  $-\Delta$  in  $\mathbb{R}^2$ .

**Ex** If you want you can  
 verify the analogous fact in  $\mathbb{R}^n$ ,  $n=3$ .

By definition

$$-\Delta E = \delta \quad (\Rightarrow) \quad - \int_{\mathbb{R}^2} E(x,y) \Delta \phi(x,y) dx dy = \phi(0,0)$$

But notice that

$$- \int_{\mathbb{R}^2} E \Delta \phi dx dy = \int_{\mathbb{R}^2} \nabla E \cdot \nabla \phi dx dy \quad \left( \begin{array}{l} E \in L^1_{loc} \\ \nabla E \in L^1_{loc} \end{array} \right)$$

Then we compute the term on the right hand side.

$$\nabla \log |(x,y)| = \nabla \log \sqrt{x^2+y^2} = \left( \frac{x}{x^2+y^2}, \frac{y}{x^2+y^2} \right)$$

$$\phi(r \cos \theta, r \sin \theta) =: \tilde{\phi}(r, \theta)$$

$$\frac{\partial}{\partial r} \tilde{\phi}(r, \theta) = \partial_x \phi(r \cos \theta, r \sin \theta) \cos \theta + \\ + \partial_y \phi(r \cos \theta, r \sin \theta) \sin \theta$$

$$\frac{\partial}{\partial \theta} \tilde{\phi}(r, \theta) = \partial_x \phi(r \cos \theta, r \sin \theta) (-r \sin \theta) + \\ + \partial_y \phi(r \cos \theta, r \sin \theta) r \cos \theta$$

Call  $A$  the jacobian matrix  $A = \begin{pmatrix} \cos \theta & \sin \theta \\ -r \sin \theta & r \cos \theta \end{pmatrix}$

of the map  $F(r, \theta) = (r \cos \theta, r \sin \theta)$

in such a way that

$$\nabla_{r, \theta} \tilde{\phi}(r, \theta) = \underbrace{\begin{pmatrix} \cos \theta & \sin \theta \\ -r \sin \theta & r \cos \theta \end{pmatrix}}_{= A} \nabla_{x, y} \phi(r \cos \theta, r \sin \theta)$$

and  $\nabla_{x, y} \phi(F(r, \theta)) = A^{-1} \nabla_{r, \theta} \tilde{\phi}(r, \theta)$  where

$$A^{-1} = \frac{1}{\det A} \begin{pmatrix} r \cos \theta & -\sin \theta \\ r \sin \theta & \cos \theta \end{pmatrix} = \frac{1}{r} \begin{pmatrix} r \cos \theta & -\sin \theta \\ r \sin \theta & \cos \theta \end{pmatrix}.$$

Then

$$\int_{\mathbb{R}^2} \nabla \log |x| \cdot \nabla \phi(x, y) dx dy = \int_{\mathbb{R}^2} \underbrace{\frac{1}{x^2 + y^2}(x, y)}_{\nabla E} \cdot \underbrace{(\partial_x \phi, \partial_y \phi)}_{\nabla \phi} dx dy =$$

$$= \int_0^{+\infty} dp \int_0^{2\pi} d\vartheta \underbrace{\rho \frac{1}{\rho^2} (\rho \cos \vartheta, \rho \sin \vartheta)}_{\mathbb{R}E} \underbrace{\frac{1}{\rho} \begin{pmatrix} \rho \cos \vartheta & -\sin \vartheta \\ \rho \sin \vartheta & \cos \vartheta \end{pmatrix}}_{A^{-1}} \nabla_{\rho, \vartheta} \tilde{\phi} =$$

$$= \int_0^{+\infty} dp \int_0^{2\pi} d\vartheta \frac{1}{\rho} (\cos \vartheta, \sin \vartheta) \begin{pmatrix} \rho \cos \vartheta \partial_\rho \tilde{\phi} - \sin \vartheta \partial_\vartheta \tilde{\phi} \\ \rho \sin \vartheta \partial_\rho \tilde{\phi} + \cos \vartheta \partial_\vartheta \tilde{\phi} \end{pmatrix} =$$

$$= \int_0^{+\infty} dp \int_0^{2\pi} d\vartheta \left[ \rho \cos^2 \vartheta \partial_\rho \tilde{\phi} - \sin \vartheta \cos \vartheta \partial_\vartheta \tilde{\phi} + \right. \\ \left. + \rho \sin^2 \vartheta \partial_\rho \tilde{\phi} + \sin \vartheta \cos \vartheta \partial_\vartheta \tilde{\phi} \right] \frac{1}{\rho} =$$

$$= \int_0^{+\infty} dp \int_0^{2\pi} d\vartheta \partial_\rho \tilde{\phi} (\rho, \vartheta) =$$

$$= \int_0^{2\pi} d\vartheta (\tilde{\phi}(+\infty, \vartheta) - \tilde{\phi}(0, \vartheta)) = -2\pi \phi(0,0)$$

since  $\tilde{\phi}(0, \vartheta) = \phi(0,0)$  (for every  $\vartheta$ )

$$\left[ \text{where } \int_0^{+\infty} \frac{d\rho}{2\sqrt{u}} \dots = \lim_{c \rightarrow +\infty} \int_0^c \dots = \right.$$

$$\left. \lim_{c \rightarrow +\infty} \int_0^c d\vartheta \left( \tilde{\Phi}(c, \vartheta) - \tilde{\Phi}(0, \vartheta) \right) = -2\sqrt{u} \phi(0, 0) \right]$$

↑ this is 0 for  $c$  big enough,  
since  $\phi$  is compactly supported.