

Oriented measures and the bang-bang principle

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Abstract – We introduce the notion of an oriented measure. The interior of the range \mathcal{R} of a non-atomic oriented measure μ is $\{\mu(E) : \chi_E \text{ has } n \text{ discontinuity points}\}$ and moreover $\mu(E) \in \partial\mathcal{R} \Leftrightarrow \chi_E$ has less than $n - 1$ discontinuity points.

Given a solution x to $x^{(n)} + a_{n-1}(t)x^{(n-1)} + \dots + a_1(t)x' + a_0(t)x \in [\phi_1, \phi_2]$ on $[a, b]$ there exist two bang-bang solutions y and z having a contact of order n with x at a and b such that $y \leqq x \leqq z$. An application to the calculus of variations yields a density result.

Mesures orientées et principe du boum-boum

Résumé – Nous introduisons la notion de mesure orientée. L'intérieur de l'image \mathcal{R} d'une mesure orientée non-atomique μ est l'ensemble $\{\mu(E) : \chi_E \text{ a } n \text{ points de discontinuité}\}$ et $\mu(E) \in \partial\mathcal{R} \Leftrightarrow \chi_E$ a au plus $n - 1$ points de discontinuité.

Si x est une solution de $x^{(n)} + a_{n-1}(t)x^{(n-1)} + \dots + a_1(t)x' + a_0(t)x \in [\phi_1, \phi_2]$ sur $[a, b]$ il existe deux solutions boum-boum y et z ayant un contact d'ordre n avec x en a et b et telles que $y \leqq x \leqq z$. Une application au calcul des variations donne un résultat de densité.

Version française abrégée – Nous introduisons la notion de mesure orientée ([3], [4]).

DÉFINITION 1. – Une mesure vectorielle $\mu = (\mu_1, \dots, \mu_n)$ sur $[a, b]$ est dite orientée si pour tout entier k dans $\{1, \dots, n\}$ et pour tout k -uplet I_1, \dots, I_k d'intervalles non-triviaux de $[a, b]$ deux à deux disjoints, le déterminant

$$\begin{vmatrix} \mu_1(I_1) & \cdots & \mu_1(I_k) \\ \vdots & \ddots & \vdots \\ \mu_k(I_1) & \cdots & \mu_k(I_k) \end{vmatrix}$$

ne s'annule pas.

Posons $\Gamma_k = \{(\gamma_1, \dots, \gamma_k) \in \mathbb{R}^k : a \leqq \gamma_1 \leqq \dots \leqq \gamma_k \leqq b\}$.

A tout k -uplet $\gamma = (\gamma_1, \dots, \gamma_k)$ de Γ_k nous associons les deux ensembles

$$E_\gamma^- = \bigcup_{\substack{0 \leq i \leq k \\ i \text{ impair}}} [\gamma_i, \gamma_{i+1}], \quad E_\gamma^+ = \bigcup_{\substack{0 \leq i \leq k \\ i \text{ pair}}} [\gamma_i, \gamma_{i+1}].$$

THÉORÈME 1. – Soit μ une mesure non-atomique orientée sur $[a, b]$ et $\rho \in L^1([a, b])$, $0 \leqq \rho \leqq 1$. Il existe deux n -uplets $\alpha = (\alpha_1, \dots, \alpha_n)$ et $\beta = (\beta_1, \dots, \beta_n)$ dans Γ_n tels que

$$(\star) \quad \mu(E_\alpha^-) = \int_a^b \rho \, d\mu = \mu(E_\beta^+).$$

Si de plus $0 < \rho < 1$ alors α et β sont les seuls éléments de Γ_n vérifiant (\star) et en outre

$$a < \alpha_1 < \dots < \alpha_n < b, \quad a < \beta_1 < \dots < \beta_n < b.$$

Nous formulons un nouveau résultat sur les solutions boum-boum d'un problème de contrôle décrit par une équation différentielle linéaire. Considérons le problème de contrôle

$$(P) \quad L(D)x = x^{(n)} + a_{n-1}(t)x^{(n-1)} + \dots + a_1(t)x' + a_0(t)x \in [\phi_1, \phi_2] \quad p.p. \text{ sur } [a, b]$$

avec a_0, \dots, a_{n-1} dans $C^{n-2}([a, b])$ et ϕ_1, ϕ_2 dans $L^1([a, b])$ telles que $\phi_1 \leqq \phi_2$.

Note présentée par Haïm BREZIS.

La fonction y est une solution boum-boum de (P) si $L(D)y \in \{\phi_1, \phi_2\}$.

THÉORÈME 2. – Soit $x \in W^{n,1}([a, b])$ une solution du problème de contrôle (P). Alors il existe deux solutions boum-boum y et z vérifiant les conditions de tangence

$$\forall k \in \{0, \dots, n-1\}, \quad y^{(k)}(a) = x^{(k)}(a) = z^{(k)}(a), \quad y^{(k)}(b) = x^{(k)}(b) = z^{(k)}(b)$$

et les inégalités $y \leqq x \leqq z$. De plus $L(D)y$ et $L(D)z$ sont de la forme $\chi_E \phi_1 + (1 - \chi_E) \phi_2$ où l'ensemble E est une réunion finie d'intervalles.

Nous appliquons ce résultat au calcul des variations.

A theorem of Lyapunov states that the range \mathcal{R} of a non-atomic vector measure μ on $[a, b]$

$$\mathcal{R} = \{\mu(A) : A \text{ measurable subset of } [a, b]\}$$

coincides with the convex set

$$\left\{ \int_a^b \rho d\mu : 0 \leqq \rho \leqq 1 \right\}.$$

However for a given ρ , $0 \leqq \rho \leqq 1$, the usual proofs based on convexity-extreme points arguments [5] are not constructive and do not give any information about the existence of a “nice” set E (for instance a finite union of intervals) such that

$$\mu(E) = \int_a^b \rho d\mu.$$

We introduce ([3], [4]) the notion of oriented measures.

DEFINITION 1. – A vector measure $\mu = (\mu_1, \dots, \mu_n)$ on $[a, b]$ is said to be oriented on $[a, b]$ if for each k in $\{1, \dots, n\}$ and for each k -tuple of non-trivial disjoint intervals I_1, \dots, I_k of $[a, b]$ the determinant

$$\begin{vmatrix} \mu_1(I_1) & \cdots & \mu_1(I_k) \\ \vdots & \ddots & \vdots \\ \mu_k(I_1) & \cdots & \mu_k(I_k) \end{vmatrix}$$

does not vanish.

We shall use the following notations: if I_1, \dots, I_n are n intervals, by $I_1 < \dots < I_n$ we mean that I_1, \dots, I_n are non-trivial and for almost all n -tuple (x_1, \dots, x_n) of $I_1 \times \dots \times I_n$ we have $x_1 < \dots < x_n$. If $\mu = (\mu_1, \dots, \mu_n)$ is a vector measure on $[a, b]$ and ρ belongs to $L^1([a, b])$, we note

$$\int_a^b \rho d\mu = \left(\int_a^b \rho d\mu_1, \dots, \int_a^b \rho d\mu_n \right).$$

We shall denote by Γ_k the set

$$\Gamma_k = \{(\gamma_1, \dots, \gamma_k) \in \mathbb{R}^k : a \leqq \gamma_1 \leqq \dots \leqq \gamma_k \leqq b\}.$$

To each k -tuple $\gamma = (\gamma_1, \dots, \gamma_k)$ belonging to Γ_k we associate the two sets

$$E_\gamma^- = \bigcup_{\substack{0 \leq i \leq k \\ i \text{ odd}}} [\gamma_i, \gamma_{i+1}], \quad E_\gamma^+ = \bigcup_{\substack{0 \leq i \leq k \\ i \text{ even}}} [\gamma_i, \gamma_{i+1}]$$

where by convention $\gamma_0 = a$, $\gamma_{k+1} = b$.

An oriented measure has the following remarkable properties:

THEOREM 3. – Let μ be a non-atomic oriented measure on $[a, b]$ and let ρ be a measurable function defined on $[a, b]$ with values in $[0, 1]$.

There exist two n -uples $\alpha = (\alpha_1, \dots, \alpha_n)$ and $\beta = (\beta_1, \dots, \beta_n)$ in Γ_n such that

$$(\star) \quad \mu(E_\alpha^-) = \int_a^b \rho d\mu = \mu(E_\beta^+).$$

If in addition $0 < \rho < 1$ then α and β in Γ_n satisfying (\star) are unique and verify

$$a < \alpha_1 < \dots < \alpha_n < b, \quad a < \beta_1 < \dots < \beta_n < b.$$

Let $\theta : \Gamma_n \rightarrow \mathcal{R}$ be the function defined by $\theta(\gamma) = \mu(E_\gamma^-)$.

PROPOSITION 1. – The interior $\overset{\circ}{\mathcal{R}}$ of the range \mathcal{R} coincides with $\left\{ \int_a^b \rho d\mu : 0 < \rho < 1 \right\}$.

THEOREM 4. – The range of θ coincides with \mathcal{R} ; the map θ induces an homeomorphism from $\overset{\circ}{\Gamma}_n$ onto $\overset{\circ}{\mathcal{R}}$ and maps $\partial\Gamma_n$ onto $\partial\mathcal{R}$.

COROLLARY 1. – If $\mu(E)$ belongs to $\partial\mathcal{R}$ and $\mu(E) = \mu(F)$ then $E \Delta F$ is negligible.

Our approach discloses the recursive structure of the boundary of the range of an oriented measure. For k belonging to $\{0, \dots, n\}$ let

$$\mathcal{R}_k^- = \{\mu(E_\gamma^-) : \gamma \in \Gamma_k\}, \quad \mathcal{R}_k^+ = \{\mu(E_\gamma^+) : \gamma \in \Gamma_k\}.$$

PROPOSITION 2. – The function $\gamma \in \overset{\circ}{\Gamma}_k \mapsto \mu(E_\gamma^-) \in \mathcal{R}_k^-$ (resp. $\gamma \in \overset{\circ}{\Gamma}_k \mapsto \mu(E_\gamma^+) \in \mathcal{R}_k^+$) is an homeomorphism from $\overset{\circ}{\Gamma}_k$ onto its range which coincides with $\overset{\circ}{\mathcal{R}}_k^-$ (resp. $\overset{\circ}{\mathcal{R}}_k^+$).

PROPOSITION 3. – The boundary of the range \mathcal{R} of an oriented non-atomic n -dimensional measure is partitioned into

$$\partial\mathcal{R} = \overset{\circ}{\mathcal{R}}_{n-1}^- \cup \dots \cup \overset{\circ}{\mathcal{R}}_1^- \cup \{0\} \cup \{\mu(a, b)\} \cup \overset{\circ}{\mathcal{R}}_1^+ \cup \dots \cup \overset{\circ}{\mathcal{R}}_{n-1}^+.$$

Let T be the symmetry with respect to $\mu(a, b)/2$. Then for each k belonging to $\{0, \dots, n\}$ we have $T(\overset{\circ}{\mathcal{R}}_k^-) = \overset{\circ}{\mathcal{R}}_k^+$, $T(\mathcal{R}_k) = \mathcal{R}_k$.

One of the essential tools for the proofs is the following lemma which allows to perturb a function leaving its integral unchanged.

LEMMA 1. – Let $\mu = (\mu_1, \dots, \mu_n)$ be a non-atomic oriented measure on the interval $[a, b]$ and $I_0 < I_1 < \dots < I_n$ be $n+1$ subintervals of $[a, b]$. Then, given a positive ϵ , there exist $n+1$ positive real numbers $\lambda_0, \dots, \lambda_n$ such that

$$\forall l \in \{0, \dots, n\}, \quad 0 < \lambda_l < \epsilon \quad \text{and} \quad \sum_{l=0}^n (-1)^l \lambda_l \mu(I_l) = 0.$$

Let μ be an absolutely continuous measure on $[a, b]$ whose density functions f_1, \dots, f_n satisfy the

ORIENTATION CONDITION Δ . – We say that n real functions f_1, \dots, f_n verify condition Δ on an interval $[a, b]$ if for each k in $\{1, \dots, n\}$, the determinant

$$\begin{vmatrix} f_1(x_1) & f_1(x_2) & \dots & f_1(x_k) \\ f_2(x_1) & f_2(x_2) & \dots & f_2(x_k) \\ \vdots & \vdots & \ddots & \vdots \\ f_k(x_1) & f_k(x_2) & \dots & f_k(x_k) \end{vmatrix}$$

is not equal to zero whenever the $x_i \in [a, b]$ are distinct and its sign is constant on the k -tuples (x_1, \dots, x_k) such that $a \leqq x_1 < x_2 < \dots < x_k \leqq b$.

Then the following nice formula

$$\begin{vmatrix} \int_{I_1} f_1 & \dots & \int_{I_k} f_1 \\ \vdots & \ddots & \vdots \\ \int_{I_1} f_k & \dots & \int_{I_k} f_k \end{vmatrix} = \int_{I_1 \times \dots \times I_k} \begin{vmatrix} f_1(s_1) & \dots & f_1(s_k) \\ f_2(s_1) & \dots & f_2(s_k) \\ \vdots & \ddots & \vdots \\ f_k(s_1) & \dots & f_k(s_k) \end{vmatrix} ds_1 \dots ds_k$$

shows that the measure μ is oriented.

We also give an operational criterion for the fulfillment of the condition Δ .

If f_1, \dots, f_{k+1} are of class C^k on $[a, b]$ we denote their Wronskian by

$$W(f_1, \dots, f_{k+1})(t) = \begin{vmatrix} f_1(t) & \dots & f_{k+1}(t) \\ \vdots & \ddots & \vdots \\ f_1^{(k)}(t) & \dots & f_{k+1}^{(k)}(t) \end{vmatrix}.$$

PROPOSITION 4. – Let $f_1, \dots, f_n \in C^{n-1}([a, b])$ be such that

$$\forall t \in [a, b], \quad W(f_1)(t) \neq 0, \dots, W(f_1, \dots, f_n)(t) \neq 0.$$

Then f_1, \dots, f_n satisfy the orientation condition Δ .

As a consequence whenever a function $x \in C^{2n-2}([a, b])$ satisfies

$$x(0) = \dots = x^{(n-2)}(0) = 0 \quad \text{and} \quad x^{(n-1)}(0) = 1$$

then the n functions $x^{(n-1)}, \dots, x'$, x verify Δ on a neighbourhood of 0. This allows us to formulate a new result concerning bang-bang solutions to linear control systems described by a generic linear differential equation. We consider the n -dimensional linear control system

$$(P) \quad L(D)x = x^{(n)} + a_{n-1}(t)x^{(n-1)} + \dots + a_1(t)x' + a_0(t)x \in [\phi_1, \phi_2] \text{ a.e. on } [a, b]$$

where the n functions a_0, \dots, a_{n-1} belong to $C^{n-2}([a, b])$ and ϕ_1, ϕ_2 in $L^1([a, b])$ verify $\phi_1 \leqq \phi_2$. The function y is said to be a bang-bang solution to (P) if $L(D)y \in \{\phi_1, \phi_2\}$.

THEOREM 5. – Let x in $W^{n,1}([a, b])$ be a solution to the control problem (P). Then there exist two bang-bang solutions y and z satisfying the tangency conditions

$$\forall k \in \{0, \dots, n-1\}, \quad y^{(k)}(a) = x^{(k)}(a) = z^{(k)}(a), \quad y^{(k)}(b) = x^{(k)}(b) = z^{(k)}(b)$$

and the inequalities $y \leqq x \leqq z$. Moreover the functions $L(D)y$ and $L(D)z$ are of the form $\chi_E \phi_1 + (1 - \chi_E) \phi_2$ where the set E is a finite union of intervals.

Finally, we give an application to the calculus of variations. We consider the problem of minimizing the integral functionals

$$I(x, u) = \int_a^b f(t, x(t), u(t)) dt$$

where $x : [a, b] \rightarrow \mathbb{R}^n$ is such that $x^{(k)}(a), x^{(k)}(b) (0 \leqq k \leqq n-1)$ are fixed and u is a control belonging to $U(t, x) \subset \mathbb{R}^n$. If $u \mapsto f(t, x, u)$ is not convex the problem does not always admit a solution. Our results yield a straightforward generalization of [1].

THEOREM 6. – *There exists a dense subset \mathcal{D} of $C(\mathbb{R})$ for the uniform convergence such that for g in \mathcal{D} the problem*

$$\min \left\{ \int_a^b g(x(t)) dt + \int_a^b h(L(D)x(t)) dt : x \in W^{n,1}([a, b]) \right\}$$

with prescribed initial and final conditions admits at least one solution for every lower semicontinuous function h satisfying the growth condition $h(u) \geq c\psi(|u|)$, ψ being l.s.c. and convex, $\lim_{r \rightarrow +\infty} \psi(r)/r = +\infty$.

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