



# Putting RUN into practice Implementation and evaluation

Davide Compagnin, Enrico Mezzetti and Tullio Vardanega University of Padua, Italy



26<sup>th</sup> EUROMICRO Conference on Real-time Systems (ECRTS) Madrid, 9 July 2014

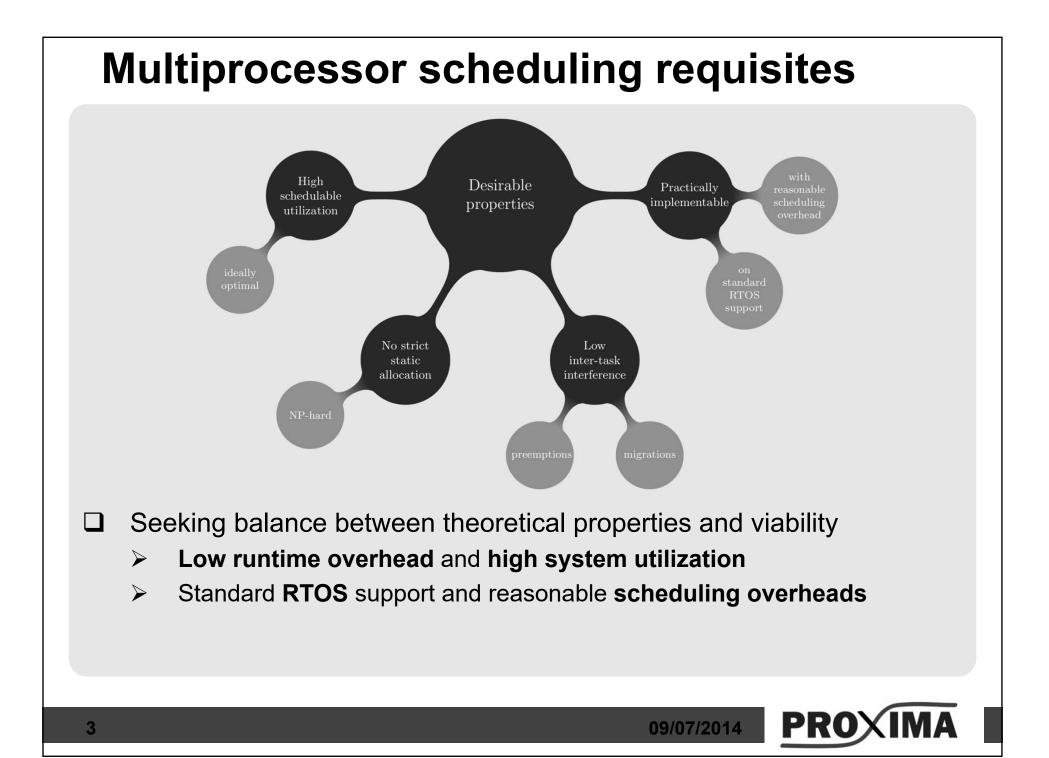
This project and the research leading to these results has received funding from the European Community's Seventh Framework Programme [FP7 / 2007-2013] under grant agreement 611085 www.proxima-project.eu

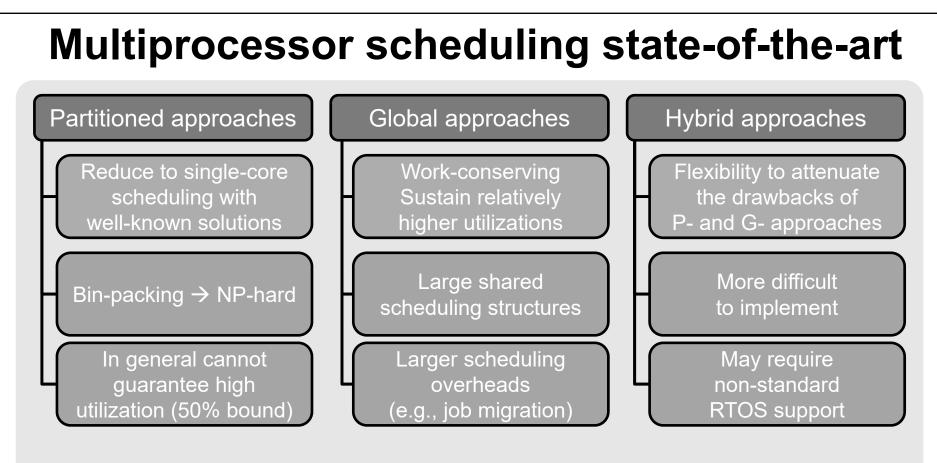
### Outline

- Motivation
- □ Brief recap of Reduction to UNiprocessor
- □ RUN implementation and evaluation
- Conclusions and future work



09/07/2014





#### Reduction to UNiprocessor (RUN)

- Optimal for implicit-deadline periodic independent tasks
- Low interference with few job migrations
- Reduces to P-EDF when a perfect partitioning exists

09/07/2014



## **Recap of the RUN algorithm**

- □ Reduction to UNiprocessor (RTSS'11)
  - Semi-partitioned algorithm (for lack of better term)
  - Optimal without resorting to proportionate fairness
- Reduction principles

 $SCHED(\mathcal{T}_n, U, m) \equiv SCHED(\mathcal{T}_n^*, n - U, n - m)$ 

Fixed-rate tasks and servers

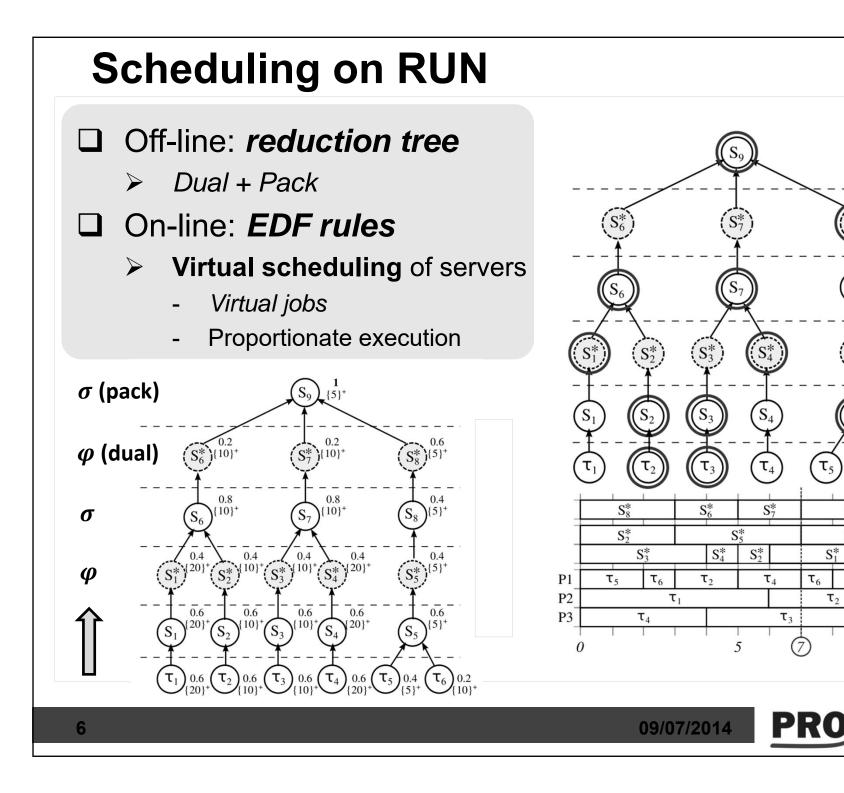
 $\tau_i \stackrel{\text{def}}{=} (\mu_i, D_i) \Rightarrow S(\sum_{\tau_i \in \mathcal{S}} \mu_i, \bigcup_{\tau_i \in \mathcal{S}} D_i)$ 

**C** Scheduling decision taken on **reduction tree** 

#### Questions

- Can it be implemented on standard RTOS support?
- What is the cost of maintaining the reduction tree at run time?

09/07/2014



 $S_8^*$ 

 $S_4^*$ 

 $\tau_5$ 

10

## **RUN** implementation

#### For real

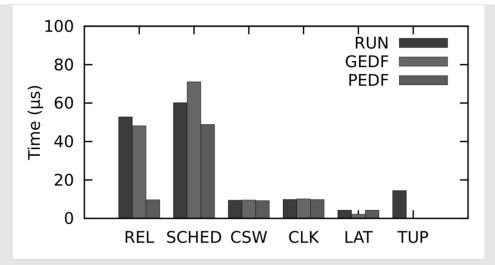
- On top of LITMUS<sup>RT</sup> Linux test-bed (UNC, now MP-SWI)
- Thus relying on an abstraction of standard RTOS support
- Main implementation choices and challenges
  - Scheduling on the reduction tree
    - How to organize the data structure
    - How to perform virtual scheduling and trigger tree updates
    - Intrinsic influence of the packing policy
  - Mixing global and local scheduling
    - Global release event queue vs. local *level-0* ready queue
    - Handling simultaneous scheduling events
      - Job release, budget exhaustion (possibly from different sub-trees)
  - > Meeting the full-utilization requirement
    - Variability of tasks' WCET and lower utilization

09/07/2014

Empirical evaluation
Empirical evaluation instead of simulation-based
<ul> <li>Focus on scheduling interference</li> <li>Cost of scheduling primitives</li> <li>Incurred preemptions and migrations</li> </ul>
<ul> <li>RUN compared against P-EDF and G-EDF</li> <li>RUN shares something in common with both</li> <li>Way better than Pfair (S-PD<sup>2</sup> in LITMUS<sup>RT</sup>)</li> <li>RUN has superior performance for preemptions and migrations</li> </ul>
8 09/07/2014 <b>PROXIMA</b>

Experimen	tal setup
LITMUS <sup>RT</sup> on	an 8-core AMD Opteron <sup>™</sup> 2356
<ul><li>Hundreds of</li><li>Harmonic and</li></ul>	asurements for RUN, P-EDF, G-EDF f automatically generated task sets nd non-harmonic, with global utilization @ 50%-100% tive of small up to large tasks
ſ	empirical determination of overheads Collect heasurements bn overheads Determine per-job upper bound Perform actual evaluation
9	09/07/2014 PROXIMA

## Primitive overheads and empirical bound

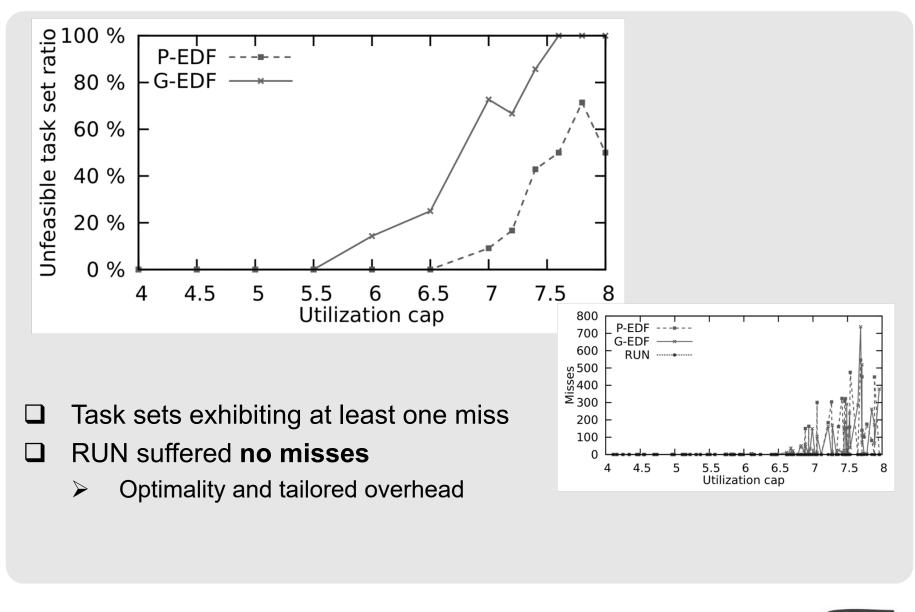


- □ Expectations confirmed
  - P-EDF needs lighter-weight scheduling primitives
- □ Tree update (TUP) triggered upon
  - Budget exhaustion event
  - ➢ Job release → REL includes TUP
- □ Empirical upper bound on RUN scheduling overhead
  - $\blacktriangleright \quad OH_{RUN}^{Job} = REL + S\widehat{CHE}D + CLK + k \times (TUP + S\widehat{CHE}D + max(PRE, MIG))$

 $k = \lceil (3p+1)/2 \rceil \text{ and } S\widehat{CHED} = SCHED + CSW + LAT.$ 



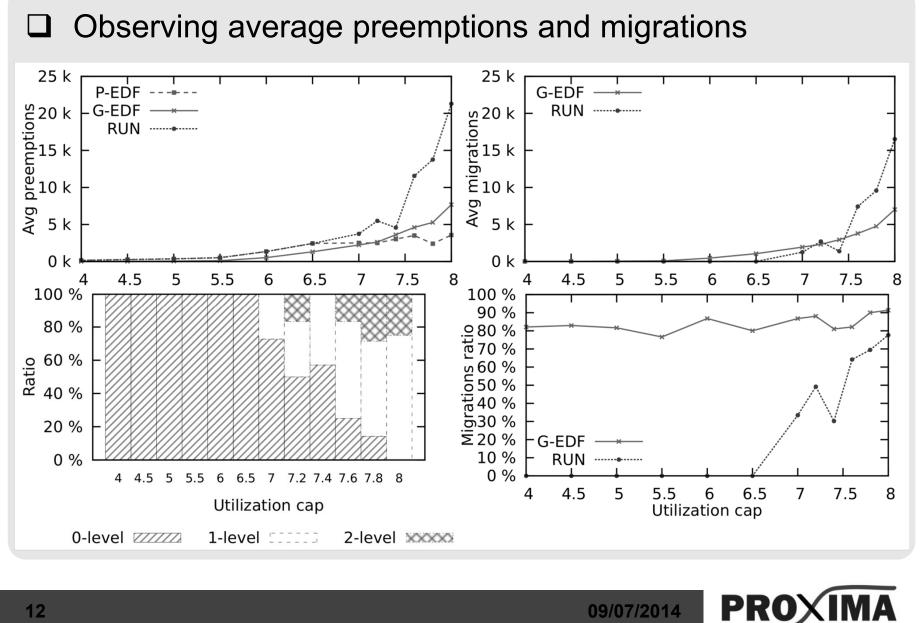
### **Empirical schedulability**



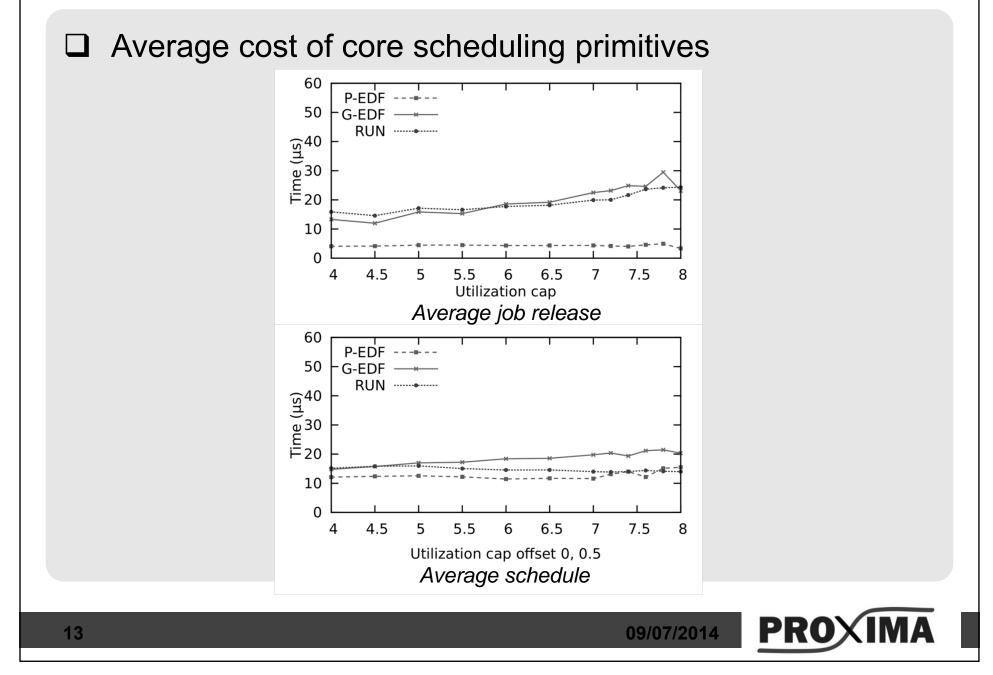
09/07/2014

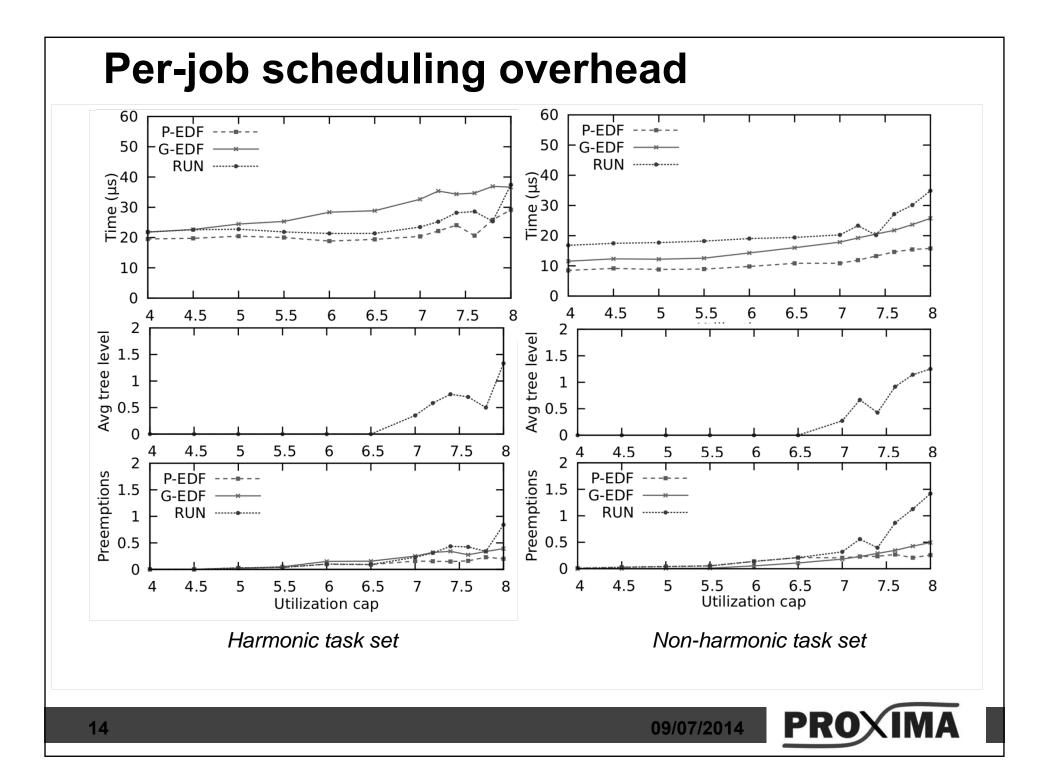
PR

### **Kernel** interference



### Scheduling cost





## **Conclusions and future work**

- Good news on RUN from this evaluation
  - It can be practically and efficiently implemented
  - It may exhibit very modest kernel overhead
    - Acceptable even on non-harmonic task sets
  - It causes a tiny amount of migrations
    - Hence low inter-task interference
- □ Essential improvements
  - Handle sporadic task sets
  - Allow sharing of *logical resources*
- □ Further work
  - Better understanding of the role of packing policies
    - Affecting the reduction tree, hence preemptions/migrations
  - Further comparisons against other optimal solutions
    - High interest in Quasi-Partitioned Scheduling (QPS)



