

Complexity of Judgment Aggregation: Safety of the Agenda

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Computational Complexity and Judgment Aggregation

Judgment aggregation is relevant for multi-agent systems

JA \iff **MAS**

Societies of agents have to **aggregate** their opinions/judgments

Is it feasible?

Computational complexity provides a first measure.

Feedback for JA:

- inspired by work on complexity of manipulation in **voting theory**;
- **precise formal** framework;
- new problems arise: **safety of the agenda**.

Outline

1. **Basic framework** of judgment aggregation in propositional logic.
2. **Safety** of the agenda: is consistency guaranteed for all aggregators?
3. **Characterisation** results for agendas: when is safety guaranteed?
4. **Complexity** results: checking safety is Π_p^2 -complete.

Basic Definitions

A set N of individuals expressing judgments on a set of correlated propositions:

Definition

An **agenda** is a finite subset of propositional formulas $\Phi \subseteq \mathcal{L}_{PS}$ closed under complementation and not containing double negations.

A **judgment set** on an agenda Φ is a subset $J \subseteq \Phi$. Call J :

Complete: if for all $\alpha \in \Phi$ either α or its complement is in J .

Complement-free: α and its complement are never both in J .

Consistent: there exists an assignment that makes all formulas in J true.

Call $J(\Phi)$ the set of all consistent and complete judgment sets.

Definition

An **aggregation procedure** for agenda Φ and a set N of n individuals is a function $F : J(\Phi)^n \rightarrow 2^\Phi$.

Axioms for Aggregation Procedures I

Aggregation procedures have been studied using the **axiomatic method**, listing axioms as desirable properties of the functions:

Weak Rationality (WR): $F(\mathbf{J})$ is complete and complement-free.

Other standard axioms are Anonymity (A), Neutrality (N), Independence (I), Systematicity (S)=(N)+(I).

We introduce two distinct forms of **monotonicity**:

I-Monotonicity (M^I): For any φ in the agenda Φ and profiles $\mathbf{J} = (J_1, \dots, J_i, \dots, J_n)$ and $\mathbf{J}' = (J_1, \dots, J'_i, \dots, J_n)$ in $J(\Phi)$, if $\varphi \notin J_i$ and $\varphi \in J'_i$, then $\varphi \in F(\mathbf{J}) \Rightarrow \varphi \in F(\mathbf{J}')$.

N-Monotonicity (M^N): For any φ, ψ in the agenda Φ and profile \mathbf{J} in $J(\Phi)$, if $\varphi \in J_i \Leftrightarrow \psi \in J_i$ for all $i \neq k$ and $\varphi \notin J_k$ and $\psi \in J_k$, then $\varphi \in F(\mathbf{J}) \Rightarrow \psi \in F(\mathbf{J})$.

Classes of Aggregation Procedures

Such axioms can be used to define different **classes of aggregation procedures**:

$$\begin{array}{ccc} \text{Set of axioms AX} & \Rightarrow & \text{Class of functions} \\ \text{Agenda } \Phi & & \mathcal{F}_\Phi[\text{AX}] \end{array}$$

Proposition (representation result)

$\mathcal{F}_\Phi[\text{WR}, A, S, M^1] = \mathcal{F}_\Phi[\text{WR}, A, N, M^N] = \mathcal{F}_\Phi[\text{WR}, A, I, M^1]$ *is the majority rule.*

We will concentrate on various weakening of the axiomatisation of majority:

$$\mathcal{F}_\Phi[\text{WR}, A, S] \quad \mathcal{F}_\Phi[\text{WR}, A, N]$$

$$\mathcal{F}_\Phi[\text{WR}, A, I] \quad \mathcal{F}_\Phi[A, S, M^1]$$

Similar **representation results** can be proved for these classes.

E.g., $\mathcal{F}_\Phi[A, S, M^1]$ is the class of uniform quota rules, (Dietrich and List, 2007)

Safety of the Agenda I

Call a function **consistent** if $F(\mathbf{J})$ is consistent for all profiles \mathbf{J} in the domain.

Possibility (characterisation) results:

There exists a consistent F in $\mathcal{F}_\Phi[\text{AX}] \Leftrightarrow \Phi$ has a certain property.

These results characterise agendas for which consistent aggregation is **possible**.

E.g., Nehring and Puppe (2006), Dietrich and List (2007), Dokow and Holzman (2005).

Safety (characterisation) results:

All F in $\mathcal{F}_\Phi[\text{AX}]$ are consistent $\Leftrightarrow \Phi$ has a certain property.

These results characterise agendas for which consistent aggregation is **guaranteed**.

Safety of the Agenda II

Definition

An agenda Φ is *safe* with respect to a class of aggregation procedures \mathcal{F}_Φ if every function in \mathcal{F}_Φ is consistent.

A discursive dilemma is a counterexample for the safety of an agenda.

Proposition

Φ is safe for $\mathcal{F}_\Phi[\text{WR}, A, S, M^1]$ iff Φ satisfies the median property MP.

Proof.

Majority rule is the only function in $\mathcal{F}_\Phi[\text{WR}, A, S, M^1]$, therefore proving the safety of Φ equals proving possibility of consistent aggregation. \square

Agenda Properties

An agenda Φ satisfies:

- the **k -median property** (k MP) for $k \geq 2$, if every inconsistent subset of Φ has itself an inconsistent subset of size at most k (2 MP= MP).
- the **simplified median property** (SMP), if every nontrivially inconsistent subset of Φ (i.e., not containing any contradictory formula) has itself an inconsistent subset of the form $\{\varphi, \psi\}$ with $\models \varphi \leftrightarrow \neg\psi$.
- the **syntactic simplified median property** (SSMP), if every nontrivially inconsistent subset of Φ has an inconsistent subset of the form $\{\varphi, \neg\varphi\}$.

$$\text{SSMP} \Rightarrow \text{SMP} \Rightarrow \text{MP} \Rightarrow k\text{MP}$$

Safety Characterisation Results

We prove the following:

Proposition

Φ is safe for $\mathcal{F}_\Phi[\text{WR}, \text{A}, \text{S}]$ if and only if Φ satisfies the SMP.

Φ is safe for $\mathcal{F}_\Phi[\text{WR}, \text{A}, \text{N}]$ if and only if Φ satisfies the SMP and does not contain a contradictory formula.

Φ is safe for $\mathcal{F}_\Phi[\text{WR}, \text{A}, \text{I}]$ if and only if Φ satisfies the SSMP.

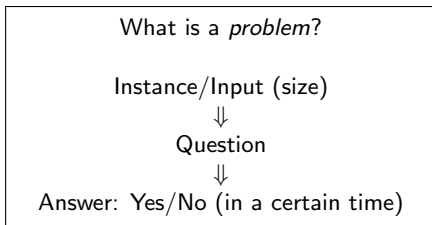
Reformulating work proved by Dietrich and List (2007) we obtain:

Proposition

Let $k \geq 2$. An agenda Φ is safe for the class of uniform quota rules F_m for n individuals satisfying $m > n - \frac{n}{k}$ if and only if Φ satisfies the k MP

Computational Complexity: what is a problem?

Computational Complexity provides a **measure** of how difficult a *problem* is, by measuring the amount of resources needed to solve it: space or **time**.



Important remarks:

- Complexity is **not** a property of a particular procedure to solve a problem.
- Complexity is **not** a property of an instance of a problem: it is a function that links the size of an input to the time required to compute the answer.

Safety of the Agenda: Identifying the problem

Our problem:
Is an agenda Φ **safe** for the class $\mathcal{F}_\Phi[AX]$?

We can define the following problem:

SAFETY[AX]

Instance: Agenda Φ of size n

Problem: Is Φ safe for $\mathcal{F}_\Phi[AX]$?

Using our characterisation, e.g. for $\mathcal{F}_\Phi[WR, A, I]$, this boils down to checking the **agenda property**:

SSMP

Instance: Agenda Φ of size n

Problem: Does Φ satisfy SSMP?

Complexity Classes: Reductions

How to **compare** two problems?

If P_1 can be “easily” translated into problem P_2
then P_2 is at least as difficult as P_1 .

Idea: there exists a **reduction** from $P_1 \leq_r P_2$
s.t. $x \in P_1 \Leftrightarrow r(x) \in P_2$

Every problem P defines the class C_P of problems that can be reduced to it.

Famous complexity classes:

- P is the class of problems solvable in polynomial time.
- NP is the class of problems solvable in non-deterministic polynomial time.

Complexity Classes: Complete Problems

Every (interesting) class C has complete problems.

P is **complete** for C if $C=C_P$

They are reference points that fully characterise their class.

SAT

Instance: Propositional formula φ

Problem: Is φ satisfiable?

SAT is **NP**-complete (Cook, 1971).

We are interested in Π_2^P , the class defined by the following satisfaction problem:

coQSAT₂

Instance: Quantified boolean formula (QBF)

$\forall x_1, \dots, x_r. \exists y_1, \dots, y_s. \varphi(x_1, \dots, x_r, y_1, \dots, y_s)$

Problem: Is the QBF satisfiable (i.e., true)?

Computational Complexity of SSMP

Checking safety turns out to be quite hard:

Theorem

SAFETY[WR, A, I] is Π_2^P -complete.

Proof.

- By characterisation this problem is equivalent to SSMP;
- SSMP is Π_2^P -complete: reduction from co-QSAT₂.



Complexity results

The following theorem is an overview of our complexity results:

Theorem

Checking the safety of an agenda is Π_2^P -complete for any of these classes of aggregation procedures:

- 1. the majority rule, corresponding to $\mathcal{F}_\Phi[\text{WR}, \text{A}, \text{S}, \text{M}^1]$, $\mathcal{F}_\Phi[\text{WR}, \text{A}, \text{I}, \text{M}^1]$, and $\mathcal{F}_\Phi[\text{WR}, \text{A}, \text{N}, \text{M}^N]$;*
- 2. systematic rules: $\mathcal{F}_\Phi[\text{WR}, \text{A}, \text{S}]$;*
- 3. neutral rules: $\mathcal{F}_\Phi[\text{WR}, \text{A}, \text{N}]$;*
- 4. independent rules: $\mathcal{F}_\Phi[\text{WR}, \text{A}, \text{I}]$;*
- 5. for any $k \geq 2$, the class of uniform quota rules F_m with $m > n - \frac{n}{k}$, where n is the number of individuals.*

Proof.

SSMP, SMP, k MP for $k \geq 2$, are all Π_2^P -complete.



Conclusions and Future Work

In conclusion:

- To the best of our knowledge the **safety** of the agenda is a new problem relevant to an application-driven study of JA.
- We have proved several characterisation results to **recognise safe agendas** for different classes of functions.
- We have proved that this problem is **Π_2^P -complete** for all classes of functions we considered.

Guaranteeing safety for various classes of functions is a very **restrictive** requirement, and checking these simple properties is **computationally hard**.

Future work includes:

- Study the complexity of the safety problem for other classes of functions.
- Introduce and study the safety of a **profile**.
- Study the complexity of **strategic manipulation** in JA.